iEthernet W5200
Datasheet
Version 1.2.5

http://www.wiznet.co.kr
W5200

The W5200 chip is a Hardwired TCP/IP embedded Ethernet controller that enables easier internet connection for embedded systems using SPI (Serial Peripheral Interface). W5200 suits best for users who need internet connectivity for application that uses a single chip to implement TCP/IP Stack, 10/100 Ethernet MAC and PHY.

The W5200 is composed of a fully hardwired market-proven TCP/IP stack and an integrated Ethernet MAC & PHY. Hardwired TCP/IP stack supports TCP, UDP, IPv4, ICMP, ARP, IGMP, and PPPoE, which has been proven in various applications for many years. W5200 uses a 32Kbytes internal buffer as its data communication memory. By using W5200, users can implement the Ethernet application they need by using a simple socket program instead of handling a complex Ethernet Controller.

SPI (Serial Peripheral Interface) is provided for easy integration with the external MCU. The W5200 SPI supports a high speed SPI capable of communicating over SPI at up to 80MHz. In order to reduce power consumption of the system, W5200 provides WOL (Wake on LAN) and power down mode. To wake up during WOL, W5200 should be received magic packet, which is the Raw Ethernet packet.

Features

- Support Hardwired TCP/IP Protocols : TCP, UDP, ICMP, IPv4 ARP, IGMP, PPPoE, Ethernet
- Supports 8 independent sockets simultaneously
- Very small 48 Pin QFN Package
- Support Power down mode
- Support Wake on LAN
- Support High Speed Serial Peripheral Interface(SPI MODE 0, 3)
- Internal 32Kbytes Memory for Tx/Rx Buffers
- 10BaseT/100BaseTX Ethernet PHY embedded
- Support Auto Negotiation (Full and half duplex, 10 and 100-based )
- Support Auto MDI/MDIX
- Support ADSL connection (with support PPPoE Protocol with PAP/CHAP Authentication mode)
- Not support IP Fragmentation
- 3.3V operation with 5V I/O signal tolerance
- Lead-Free Package
- Multi-function LED outputs (Full/Half duplex, Link, Speed)
Target Applications

The W5200 is well suited for many embedded applications, including:

- Home Network Devices: Set-Top Boxes, PVRs, Digital Media Adapters
- Serial-to-Ethernet: Access Controls, LED displays, Wireless AP relays, etc.
- Parallel-to-Ethernet: POS / Mini Printers, Copiers
- USB-to-Ethernet: Storage Devices, Network Printers
- GPIO-to-Ethernet: Home Network Sensors
- Security Systems: DVRs, Network Cameras, Kiosks
- Factory and Building Automations
- Medical Monitoring Equipments
- Embedded Servers
Block Diagram

W5200

- MCU
- SPI Interface
- Tx/Rx Buffer
- Hardwired TCP/IP Core
  - TCP
  - UDP
  - PPPoE
  - ARP
  - IP
  - 802.3 Ethernet MAC
- Ethernet PHY
- Transformer
- RJ45

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### 1.1 MCU Interface Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
</table>
| nRST   | 1    | 46     | RESET (Active LOW)  
This pin is active Low input to initialize or re-initialize W5200.  
RESET should be held at least 2us after low assert, and wait for at least 150ms after high de-assert in order for PLL logic to be stable. Refer to RESET timing of “7 Electrical Specification” |
| nSCS   | 1    | 41     | SPI SLAVE SELECT (Active LOW)  
This pin is used to SPI Slave Select signal Pin when using SPI interface. |
| nINT   | 0    | 40     | INTERRUPT (Active LOW)  
This pin indicates that W5200 requires MCU attention after socket connecting, disconnecting, data receiving timeout, and WOL (Wake on LAN). The interrupt is
cleared by writing IR(Interrupt Register) or Sn_IR (Socket n-th Interrupt Register). All interrupts are maskable. This pin is active low.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SCLK</td>
<td>I</td>
<td>42</td>
<td>SPI CLOCK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin is used to SPI Clock signal Pin when using SPI interface.</td>
</tr>
<tr>
<td>MOSI</td>
<td>I</td>
<td>43</td>
<td>SPI MASTER OUT SLAVE IN</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin is used to SPI MOSI signal pin when using SPI interface.</td>
</tr>
<tr>
<td>MISO</td>
<td>O</td>
<td>44</td>
<td>SPI MASTER IN SLAVE OUT</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin is used to SPI MISO signal pin.</td>
</tr>
<tr>
<td>PWDN</td>
<td>I</td>
<td>45</td>
<td>POWER DOWN ( Active HIGH )</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin is used to power down pin. Low : Normal Mode Enable High : Power Down Mode Enable</td>
</tr>
</tbody>
</table>

### 1.2 PHY Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RXIP</td>
<td>I</td>
<td>20</td>
<td>RXIP/RXIN Signal Pair</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The differential data from the media is received on the RXIP/RXIN signal pair.</td>
</tr>
<tr>
<td>RXIN</td>
<td>I</td>
<td>21</td>
<td>RXIP/RXIN Signal Pair</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The differential data from the media is received on the RXIP/RXIN signal pair.</td>
</tr>
<tr>
<td>TXOP</td>
<td>O</td>
<td>17</td>
<td>TXOP/TXON Signal Pair</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The differential data is transmitted to the media on the TXOP/TXON signal pair.</td>
</tr>
<tr>
<td>TXON</td>
<td>O</td>
<td>18</td>
<td>TXOP/TXON Signal Pair</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The differential data is transmitted to the media on the TXOP/TXON signal pair.</td>
</tr>
<tr>
<td>BIAS</td>
<td>O</td>
<td>12</td>
<td>BIAS Register</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Connect a resistor of 28.7kΩ±1% to the ground. Refer to the “Reference schematic”.</td>
</tr>
<tr>
<td>ANE</td>
<td>I</td>
<td>29</td>
<td>Auto Negotiation Mode Enable</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin selects Enable/Disable of Auto Negotiation Mode. Low : Auto Negotiation Mode Disable High : Auto Negotiation Mode Enable</td>
</tr>
<tr>
<td>DUP</td>
<td>I</td>
<td>30</td>
<td>Full Duplex Mode Enable</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>This pin selects Enable/Disable of Full Duplex Mode. Low = Half Duplex Mode Enable High = Full Duplex Mode Enable</td>
</tr>
<tr>
<td>SPD</td>
<td>I</td>
<td>31</td>
<td>Speed Mode</td>
</tr>
</tbody>
</table>

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This pin selects 100M/10M Speed Mode.
Low = 10M Speed Mode
High = 100M Speed Mode
This function activates only during reset period.

1.3 Miscellaneous Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nFDXLED/M2</td>
<td>I</td>
<td>3, 4, 5</td>
<td>W5200 MODE SELECT</td>
</tr>
<tr>
<td>nSPDLED/M1</td>
<td>I</td>
<td>4</td>
<td>Normal mode : 111</td>
</tr>
<tr>
<td>nLINKLED/M0</td>
<td>I</td>
<td>5</td>
<td>Other test modes are internal test mode. This function activates only during reset period</td>
</tr>
<tr>
<td>M3</td>
<td>I</td>
<td>6</td>
<td>This pin should be pull-up.</td>
</tr>
<tr>
<td>RSV</td>
<td>-</td>
<td>7, 32, 33, 34, 35, 36, 37, 38, 39</td>
<td>Reserved Pin The pin number 7 should be pull-up. The reserved pins except the pin number 7 should be pull-down or GND.</td>
</tr>
</tbody>
</table>

- Notes: Pull-Up/Down register = 40KΩ to 100KΩ. Typical value are 75KΩ.

1.4 Power Supply Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCC3V3A</td>
<td>Power</td>
<td>11, 15, 23</td>
<td>3.3V power supply for Analog part</td>
</tr>
<tr>
<td>VCC3V3</td>
<td>Power</td>
<td>27, 47</td>
<td>3.3V power supply for Digital part</td>
</tr>
<tr>
<td>VCC1V8</td>
<td>Power</td>
<td>8, 25</td>
<td>1.8V power supply for Digital part</td>
</tr>
<tr>
<td>GNDA</td>
<td>Ground</td>
<td>13, 19, 22, 24</td>
<td>Analog ground</td>
</tr>
<tr>
<td>GND</td>
<td>Ground</td>
<td>9, 10, 26, 28, 48</td>
<td>Digital ground</td>
</tr>
<tr>
<td>1V8O</td>
<td>0</td>
<td>14</td>
<td>1.8V regulator output voltage 1.8V/200mA power created by internal power regulator, is used for core operation power (VCC1V8). Be sure to connect tantalum capacitor between 1V8O and GND for output frequency compensation, and selectively connect 0.1uF capacitor for high frequency noise decoupling. Notice: 1V8O is the power for W5200 core operation. It should not be connected to the power of other devices.</td>
</tr>
</tbody>
</table>
Figure 2 XTAL_VDD Reference Schematic
Connect a capacitor of 10.1μF to the ground.
※ Refer to the ‘W5200E01-M3 Reference schematic

Figure 3 Power Design

Recommend for power design.

1. Locate decoupling capacitor as close as possible to W5200.
2. Use ground plane as wide as possible.
3. If ground plane width is adequate, having a separate analog ground plane and digital ground plane is good practice.
4. If ground plane is not wide, design analog and digital ground planes as a single ground plane, rather than separate them.

1.5 Clock Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>XI</td>
<td>I</td>
<td>1</td>
<td>25MHz crystal input/output. A 25MHz crystal and Oscillator is used to connect these pins.</td>
</tr>
<tr>
<td>XO</td>
<td>O</td>
<td>2</td>
<td></td>
</tr>
</tbody>
</table>

![Figure 4 Crystal Reference Schematic](image)

1.6 LED Signals

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Type</th>
<th>Pin No</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nFDXLED/M2</td>
<td>O</td>
<td>3</td>
<td>Full Duplex/Collision LED</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Low: Full-duplex</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>High: Half-duplex</td>
</tr>
<tr>
<td>nSPDLED/M1</td>
<td>O</td>
<td>4</td>
<td>Link speed LED</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Low: 100Mbps</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>High: 10Mbps</td>
</tr>
<tr>
<td>nLINKLED/M0</td>
<td>O</td>
<td>5</td>
<td>Link LED</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Low: Link (10/100M)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>High: Un-Link</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>blink: TX or RX state on Link</td>
</tr>
</tbody>
</table>
2 Memory Map

W5200 is composed of Common Register, Socket Register, TX Memory, and RX Memory as shown below.
3 W5200 Registers

3.1 common registers

<table>
<thead>
<tr>
<th>Address</th>
<th>Register</th>
<th>Address</th>
<th>Register</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0000</td>
<td>Mode (MR)</td>
<td>0x001C</td>
<td>Authentication Type in PPPoE</td>
</tr>
<tr>
<td>0x0001</td>
<td>Gateway Address (GAR0)</td>
<td>0x001D</td>
<td>(PATR0)</td>
</tr>
<tr>
<td>0x0002</td>
<td>(GAR1)</td>
<td>0x001E</td>
<td>Authentication Algorithm in PPPoE (PPPALGO)</td>
</tr>
<tr>
<td>0x0003</td>
<td>(GAR2)</td>
<td>0x001F</td>
<td>Chip version (VERSIONR)</td>
</tr>
<tr>
<td>0x0004</td>
<td>(GAR3)</td>
<td>0x0020</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x0005</td>
<td>Subnet mask Address (SUBR0)</td>
<td>0x0027</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x0006</td>
<td>(SUBR1)</td>
<td>0x0028</td>
<td>PPP LCP RequestTimer</td>
</tr>
<tr>
<td>0x0007</td>
<td>(SUBR2)</td>
<td>0x0029</td>
<td>(PTIMER)</td>
</tr>
<tr>
<td>0x0008</td>
<td>(SUBR3)</td>
<td>0x002A</td>
<td>PPP LCP Magic number (PMAGIC)</td>
</tr>
<tr>
<td>0x0009</td>
<td>Source Hardware Address (SHAR0)</td>
<td>0x002F</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x000A</td>
<td>(SHAR1)</td>
<td>0x0030</td>
<td>Interrupt Low Level Timer</td>
</tr>
<tr>
<td>0x000B</td>
<td>(SHAR2)</td>
<td>0x0031</td>
<td>(INLEVEL0)</td>
</tr>
<tr>
<td>0x000C</td>
<td>(SHAR3)</td>
<td>0x0032</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x000D</td>
<td>(SHAR4)</td>
<td>0x0033</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x000E</td>
<td>(SHAR5)</td>
<td>0x0034</td>
<td>Socket Interrupt (IR2)</td>
</tr>
<tr>
<td>0x000F</td>
<td>Source IP Address (SIPR0)</td>
<td>0x0035</td>
<td>PHY Status (PSTATUS)</td>
</tr>
<tr>
<td>0x0010</td>
<td>(SIPR1)</td>
<td>0x0036</td>
<td>Interrupt Mask (IMR)</td>
</tr>
<tr>
<td>0x0011</td>
<td>(SIPR2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0012</td>
<td>(SIPR3)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0013</td>
<td>Reserved</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0014</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0015</td>
<td>Interrupt (IR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0016</td>
<td>Socket Interrupt Mask (IMR2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0017</td>
<td>Retry Time (RTR0)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0018</td>
<td>(RTR1)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x0019</td>
<td>Retry Count (RCR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x001A</td>
<td>Reserved</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x001B</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### 3.2 Socket registers

Note: n is socket number (0, 1, 2, 3, 4, 5, 6, 7)

<table>
<thead>
<tr>
<th>Address</th>
<th>Register</th>
<th>Address</th>
<th>Register</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4n00</td>
<td>Socket n Mode (Sn_MR)</td>
<td>0x4n1E</td>
<td>Receive Memory Size</td>
</tr>
<tr>
<td>0x4n01</td>
<td>Socket n Command (Sn_CR)</td>
<td>0x4n1F</td>
<td>Transmit Memory Size</td>
</tr>
<tr>
<td>0x4n02</td>
<td>Socket n Interrupt (Sn_IR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x4n03</td>
<td>Socket n Status (Sn_SR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Socket n SourcePort</td>
<td>0x4n20</td>
<td>Socket 0 TX Free Size</td>
</tr>
<tr>
<td>0x4n04</td>
<td>(SN_PORT0)</td>
<td>0x4n21</td>
<td>(Sn_TX_FSR0)</td>
</tr>
<tr>
<td>0x4n05</td>
<td>(SN_PORT1)</td>
<td></td>
<td>(Sn_TX_FSR1)</td>
</tr>
<tr>
<td></td>
<td>Socket n Destination Hardware</td>
<td>0x4n22</td>
<td>Socket 0 TX Read Pointer</td>
</tr>
<tr>
<td>0x4n06</td>
<td>Address</td>
<td>0x4n23</td>
<td>(Sn_TX_RD0)</td>
</tr>
<tr>
<td>0x4n07</td>
<td>(Sn_DHAR0)</td>
<td></td>
<td>(Sn_TX_RD1)</td>
</tr>
<tr>
<td>0x4n08</td>
<td>(Sn_DHAR1)</td>
<td>0x4n24</td>
<td>Socket 0 TX Write Pointer</td>
</tr>
<tr>
<td>0x4n09</td>
<td>(Sn_DHAR2)</td>
<td>0x4n25</td>
<td>(Sn_TX_WR0)</td>
</tr>
<tr>
<td>0x4n0A</td>
<td>(Sn_DHAR3)</td>
<td></td>
<td>(Sn_TX_WR1)</td>
</tr>
<tr>
<td>0x4n0B</td>
<td>(Sn_DHAR4)</td>
<td>0x4n26</td>
<td>Socket 0 RX Received Size</td>
</tr>
<tr>
<td></td>
<td>(Sn_DHAR5)</td>
<td>0x4n27</td>
<td>(Sn_RX_RSR0)</td>
</tr>
<tr>
<td></td>
<td>Socket 0 Destination IP Address</td>
<td></td>
<td>(Sn_RX_RSR1)</td>
</tr>
<tr>
<td>0x4n0C</td>
<td>Address</td>
<td>0x4n28</td>
<td>Socket 0 RX Read Pointer</td>
</tr>
<tr>
<td>0x4n0D</td>
<td>(Sn_DIPR0)</td>
<td>0x4n29</td>
<td>(Sn_RX_RD0)</td>
</tr>
<tr>
<td>0x4n0E</td>
<td>(Sn_DIPR1)</td>
<td></td>
<td>(Sn_RX_RD1)</td>
</tr>
<tr>
<td>0x4n0F</td>
<td>(Sn_DIPR2)</td>
<td>0x4n2A</td>
<td>Socket 0 RX Write Pointer</td>
</tr>
<tr>
<td></td>
<td>(Sn_DIPR3)</td>
<td>0x4n2B</td>
<td>(Sn_RX_WR0)</td>
</tr>
<tr>
<td></td>
<td>Socket 0 Destination Port</td>
<td></td>
<td>(Sn_RX_WR1)</td>
</tr>
<tr>
<td>0x4n10</td>
<td>(Sn_DPORT0)</td>
<td>0x4n2C</td>
<td>Socket Interrupt Mask</td>
</tr>
<tr>
<td>0x4n11</td>
<td>(Sn_DPORT1)</td>
<td></td>
<td>(Sn_IMR)</td>
</tr>
<tr>
<td></td>
<td>Socket 0 Maximum Segment Size</td>
<td>0x4n2D</td>
<td>Fragment Offset in IP header</td>
</tr>
<tr>
<td>0x4n12</td>
<td>(Sn_MSSR0)</td>
<td>0x4n2E</td>
<td>(Sn_FRAG0)</td>
</tr>
<tr>
<td>0x4n13</td>
<td>(Sn_MSSR1)</td>
<td></td>
<td>(Sn_FRAG1)</td>
</tr>
<tr>
<td></td>
<td>Socket 0 Protocol in IP Raw mode</td>
<td>0x4n30</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x4n14</td>
<td>(Sn_PROTO)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Socket n IP TOS (Sn_TOS)</td>
<td>0x4nFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Socket n IP TTL (Sn_TTL)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x4n17</td>
<td>-</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x4n1D</td>
<td>Reserved</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
4 Register Descriptions

4.1 Common Registers

MR (Mode Register) [R/W] [0x0000] [0x00]

This register is used for S/W reset, ping block mode and PPPoE mode.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>RST</td>
<td>S/W Reset</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If this bit is ‘1’, internal register will be initialized. It will be automatically cleared after reset.</td>
</tr>
<tr>
<td>6</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>5</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>4</td>
<td>PB</td>
<td>Ping Block Mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 : Disable Ping block</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Enable Ping block</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If the bit is set as ‘1’, there is no response to the ping request.</td>
</tr>
<tr>
<td>3</td>
<td>PPPoE</td>
<td>PPPoE Mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 : Disable PPPoE mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Enable PPPoE mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If you use ADSL without router or etc, you should set the bit as ‘1’ to connect to ADSL Server. For more detail, refer to the application note, “How to connect ADSL”.</td>
</tr>
<tr>
<td>2</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>1</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>0</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

GAR (Gateway IP Address Register) [R/W] [0x0001 - 0x0004] [0x00]

This Register sets up the default gateway address.

Ex) In case of “192.168.0.1”

<table>
<thead>
<tr>
<th>0x0001</th>
<th>0x0002</th>
<th>0x0003</th>
<th>0x0004</th>
</tr>
</thead>
<tbody>
<tr>
<td>192 (0xC0)</td>
<td>168 (0xA8)</td>
<td>0 (0x00)</td>
<td>1 (0x01)</td>
</tr>
</tbody>
</table>

SUBR (Subnet Mask Register) [R/W] [0x0005 - 0x0008] [0x00]

This register sets up the subnet mask address.

Ex) In case of “255.255.255.0”
SHAR (Source Hardware Address Register) [R/W] [0x0009 - 0x000E] [0x00]
This register sets up the Source Hardware address.
Ex) In case of “00.08.DC.01.02.03”

<table>
<thead>
<tr>
<th>0x0009</th>
<th>0x000A</th>
<th>0x000B</th>
<th>0x000C</th>
<th>0x000D</th>
<th>0x000E</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x08</td>
<td>0xDC</td>
<td>0x01</td>
<td>0x02</td>
<td>0x03</td>
</tr>
</tbody>
</table>

SIPR (Source IP Address Register) [R/W] [0x000F - 0x0012] [0x00]
This register sets up the Source IP address.
Ex) In case of “192.168.0.2”

<table>
<thead>
<tr>
<th>0x000F</th>
<th>0x0010</th>
<th>0x0011</th>
<th>0x0012</th>
</tr>
</thead>
<tbody>
<tr>
<td>192</td>
<td>168</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

IR (Interrupt Register) [R] [0x0015] [0x00]
This register is accessed by the host processor to know the cause of interrupt. Any interruption can be masked in the Interrupt Mask Register (IMR). The nINT signal retain low as long as any masked signal is set, and will not go high until all masked bits in this Register have been cleared.

<table>
<thead>
<tr>
<th>7</th>
<th>6</th>
<th>5</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONFLICT</td>
<td>Reserved</td>
<td>PPPoE</td>
<td>Reserved</td>
<td>Reserved</td>
<td>Reserved</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
</table>
| 7   | CONFLICT | IP Conflict
It is set as ‘1’ when there is ARP request with same IP address as Source IP address. This bit is cleared to ‘0’ by writing ‘1’ to this bit. |
| 6   | Reserved | Reserved |
| 5   | PPPoE   | PPPoE Connection Close
In the Point-to-Point Protocol over Ethernet (PPPoE) Mode, if the PPPoE connection is closed, ‘1’ is set. This bit will be cleared to ‘0’ by writing ‘1’ to this bit. |
| 4   | Reserved | Reserved |
| 3   | Reserved | Reserved |
| 2   | Reserved | Reserved |
| 1   | Reserved | Reserved |
| 0   | Reserved | Reserved |
IMR (Interrupt Mask Register) [R/W] [0x0036] [0x00]

The Interrupt Mask Register is used to mask interrupts. Each interrupt mask bit corresponds to a bit in the Interrupt Register (IR). If an interrupt mask bit is set, an interrupt will be issued whenever the corresponding bit in the IR is set. If any bit in the IMR is set as ‘0’, an interrupt will not occur though the bit in the IR is set.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>IM_IR7</td>
<td>IP Conflict Enable</td>
</tr>
<tr>
<td>6</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>5</td>
<td>IM_IR5</td>
<td>PPPoE Close Enable</td>
</tr>
<tr>
<td>4</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>3</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>2</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>1</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>0</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

RTR (Retry Time-value Register) [R/W] [0x0017 - 0x0018] [0x07D0]

It configures the retransmission timeout-period. The standard unit of RTR is 100us. RTR is initialized with 2000(0x07D0) and has 200ms timeout-period.

Ex) When timeout-period is set as 400ms, \( RTR = \frac{400\text{ms}}{1\text{ms}} \times 10 = 4000(0x0FA0) \)

<table>
<thead>
<tr>
<th>RTR</th>
<th>0x0017</th>
<th>0x0018</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0xF</td>
<td>0xA0</td>
</tr>
</tbody>
</table>

Re-transmission will occur if there is no response from the remote peer to the commands of CONNECT, DISCON, CLOSE, SEND, SEND_MAC and SEND_KEEP, or the response is delayed.

RCR (Retry Count Register) [R/W] [0x0019] [0x08]

It configures the number of retransmission times. When retransmission occurs as many as ‘RCR+1’ times, Timeout interrupt is set (‘TIMEOUT’ bit of Sn_IR is set as ‘1’).

In case of using TCP communication, the value of Sn_SR (Socket n-th Status Register) is changed to ‘SOCK_CLOSED’ and Sn_IR(Socket n-th Status Register) (TIMEOUT) turns into ‘1’. In case of not using TCP communication, only Sn_IR(TIMEOUT) turns into ‘1’.

Ex) \( RCR = 0x0007 \)
The timeout of W5200 can be configurable with RTR and RCR. W5200’s timeout has Address Resolution Protocol (ARP) and TCP retransmission timeout.

At the ARP (Refer to RFC 826, http://www.ietf.org/rfc.html) retransmission timeout, W5200 automatically sends ARP-request to the peer’s IP address in order to acquire MAC address information (used for communication of IP, UDP, or TCP). As waiting for ARP-response from the peer, if there is no response during the time set in RTR, Timeout occurs and ARP-request is retransmitted. It is repeated as many as ‘RCR + 1’ times.

Even after ARP-request retransmissions are repeated ‘RCR + 1’ times, if there is no ARP-response, the final timeout occurs and Sn_IR(TIMEOUT) becomes ‘1’.

The value of final timeout (ARP_TO) of ARP-request is as below.

\[ \text{ARP}_{\text{TO}} = (\text{RTR} \times 0.1\text{ms}) \times (\text{RCR} + 1) \]

At the TCP packet retransmission timeout, W5200 transmits TCP packets (SYN, FIN, RST, DATA packets) and waits for the acknowledgement (ACK) during the time set in RTR and RCR. If there is no ACK from the peer, Timeout occurs and TCP packets (sent earlier) are retransmitted. The retransmissions are repeated as many as ‘RCR + 1’ times. Even after TCP packet retransmissions are repeated ‘RCR +1’ times, if there is no ACK from the peer, final timeout occurs and Sn_SR is changed to ‘SOCK_CLOSED” at the same time with Sn_IR(TIMEOUT) = ‘1’

\[ \text{TCP}_{\text{TO}} = \left( \sum_{N=0}^{M} (\text{RTR} \times 2^N) \right) + ((\text{RCR} - M) \times \text{RTR}_{\text{MAX}}) \times 0.1\text{ms} \]

\[ \text{TCP}_{\text{TO}} = \left( 0x07D0 \times 2^0 + 0x07D0 \times 2^1 + 0x07D0 \times 2^2 + 0x07D0 \times 2^3 + 0x07D0 \times 2^4 \right) \times 0.1\text{ms} \]

\[ \text{TCP}_{\text{TO}} = \left( 2000 + 4000 + 8000 + 16000 + 32000 + \ldots + 318000 \right) \times 0.1\text{ms} \]

Ex) When RTR = 2000(0x07D0), RCR = 8(0x0008),

\[ \text{ARP}_{\text{TO}} = 2000 \times 0.1\text{ms} \times 9 = 1800\text{ms} = 1.8s \]

\[ \text{TCP}_{\text{TO}} = (0x07D0 + 0x0FA0 + 0x1F40 + 0x3E80 + 0x7D00 + 0xFA00 + 0xFA00 + 0xFA00 + 0xFA00) \times 0.1\text{ms} \]

\[ = (2000 + 4000 + 8000 + 16000 + 32000 + \ldots + 318000) \times 0.1\text{ms} \]

\[ = 318000 \times 0.1\text{ms} = 31.8s \]

The value of final timeout (TCP_TO) of TCP packet retransmission can be calculated as below,

**PATR (Authentication Type in PPPoE mode) [R] [0x001C-0x001D] [0x0000]**

This register notifies authentication method that has been agreed at the connection with PPPoE Server. W5200 supports two types of Authentication method - PAP and CHAP.

<table>
<thead>
<tr>
<th>Value</th>
<th>Authentication Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC023</td>
<td>PAP</td>
</tr>
<tr>
<td>0xC223</td>
<td>CHAP</td>
</tr>
</tbody>
</table>
PPPALGO (Authentication Algorithm in PPPoE mode) [R][0x001E][0x00]
This register notifies authentication algorithm in PPPoE mode. For detailed information, please refer to PPPoE application note.

VERSIONR (W5200 Chip Version Register) [R][0x001F][0x03]
This register is the W5200 chip version register.

PTIMER (PPP Link Control Protocol Request Timer Register) [R/W][0x0028]
This register indicates the duration for sending LCP Echo Request. Value 1 is about 25ms.
Ex) in case that PTIMER is 200,
    \[200 \times 25\text{ms} = 5000\text{ms} = 5 \text{ seconds}\]

PMAGIC (PPP Link Control Protocol Magic number Register) [R/W][0x0029][0x00]
This register is used in Magic number option during LCP negotiation. Refer to the application note, “How to connect ADSL”.

INTLEVEL (Interrupt Low Level Timer Register) [R/W][0x0030 - 0x0031][0x0000]
It sets Interrupt Assert wait time (I_{AWT}). It configures nINT Low Assert waiting time until the next interrupt.

\[
I_{AWT} = (\text{INTLEVEL} + 1) \times \text{PLL_CLK} \quad \text{(when INTLEVEL > 0)}
\]

![Figure 5 INTLEVEL Timing](image)

a. At SOCKET 0, Receive Interrupt occurs (S0_IR(3) = ‘1’) and corresponding IR2 bit is set as ‘1’ (IR(S0_IR) = ‘1’). nINT signal is asserted low.
b. At SOCKET 1, Connected Interrupt occurs (S1_IR(0) = ‘1’) and corresponding IR2 bit set as ‘1’ (IR(S1_IR) = ‘1’).
c. The Host clears S0_IR1 (S0_IR = 0x00) and corresponding IR bit is automatically cleared (IR(S0_IR) = ‘0’). nINT signal becomes High.
d. S0_IR is cleared. As IR2 is not 0x00, nINT should be asserted low right after 1PLL_CLK. However, as INTLEVEL is 0x000F, the interrupt about IR is processed after I_{AWT}(16 PLL_CLK).
IR2(W5200 SOCKET Interrupt Register)[R/W][0x0034][0x00]

IR2 is the Register to notify W5200 SOCKET interrupt to the Host. If any interrupt occurs, the related bit of IR2 is set as ‘1’. When related Mask Bit is ‘1’, nINT signal is asserted low. nINT keeps low until all bits of Sn_IR becomes ‘0’. If all bits of Sn_IR become ‘0’, it becomes high automatically.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>S7_INT</td>
<td>When an interrupt occurs at SOCKET 7-th, it becomes ‘1’. This interrupt information is applied to S7_IR. This bit is automatically cleared when S7_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>6</td>
<td>S6_INT</td>
<td>When an interrupt occurs at SOCKET 6-th, it becomes ‘1’. This interrupt information is applied to S6_IR. This bit is automatically cleared when S6_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>5</td>
<td>S5_INT</td>
<td>When an interrupt occurs at SOCKET 5-th, it becomes ‘1’. This interrupt information is applied to S5_IR. This bit is automatically cleared when S5_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>4</td>
<td>S4_INT</td>
<td>When an interrupt occurs at SOCKET 4-th, it becomes ‘1’. This interrupt information is applied to S4_IR. This bit is automatically cleared when S4_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>3</td>
<td>S3_INT</td>
<td>When an interrupt occurs at SOCKET 3-th, it becomes ‘1’. This interrupt information is applied to S3_IR. This bit is automatically cleared when S3_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>2</td>
<td>S2_INT</td>
<td>When an interrupt occurs at SOCKET 2-th, it becomes ‘1’. This interrupt information is applied to S2_IR. This bit is automatically cleared when S2_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>1</td>
<td>S1_INT</td>
<td>When an interrupt occurs at SOCKET 1-th, it becomes ‘1’. This interrupt information is applied to S1_IR. This bit is automatically cleared when S1_IR is cleared to 0x00 by host.</td>
</tr>
<tr>
<td>0</td>
<td>S0_INT</td>
<td>When an interrupt occurs at SOCKET 0-th, it becomes ‘0’. This interrupt information is applied to S0_IR. This bit is automatically cleared when S0_IR is cleared to 0x00 by host.</td>
</tr>
</tbody>
</table>
### PHYSTATUS (W5200 PHY status Register) [R/W] [0x0035][0x00]

PHYSTATUS is the Register to indicate W5200 status of PHY.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>6</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>5</td>
<td>LINK</td>
<td>Link Status Register [Read Only]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This register indicates Link status.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 : Link down</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Link Up</td>
</tr>
<tr>
<td>4</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>3</td>
<td>POWERDOWN</td>
<td>Power down mode of PHY [Read Only]</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This register indicates status of Power down mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 : Disable Power down mode (operates normal mode)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Enable Power down mode</td>
</tr>
<tr>
<td>2</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>1</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
<tr>
<td>0</td>
<td>Reserved</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

### IMR2 (Interrupt Mask Register2) [R/W] [0x016][0x00]

The Interrupt Mask Register is used to mask interrupts. Each interrupt mask bit corresponds to a bit in the Interrupt Register2 (IR2). If an interrupt mask bit is set, an interruption will be issued whenever the corresponding bit in the IR2 is set. If any bit in the IMR is set as ‘0’ an interrupt will not occur though the bit.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>S7_INT</td>
<td>IR(S7_INT) Interrupt Mask</td>
</tr>
<tr>
<td>6</td>
<td>S6_INT</td>
<td>IR(S6_INT) Interrupt Mask</td>
</tr>
<tr>
<td>5</td>
<td>S5_INT</td>
<td>IR(S5_INT) Interrupt Mask</td>
</tr>
<tr>
<td>4</td>
<td>S4_INT</td>
<td>IR(S4_INT) Interrupt Mask</td>
</tr>
<tr>
<td>3</td>
<td>S3_INT</td>
<td>IR(S3_INT) Interrupt Mask</td>
</tr>
<tr>
<td>2</td>
<td>S2_INT</td>
<td>IR(S2_INT) Interrupt Mask</td>
</tr>
<tr>
<td>1</td>
<td>S1_INT</td>
<td>IR(S1_INT) Interrupt Mask</td>
</tr>
<tr>
<td>0</td>
<td>S0_INT</td>
<td>IR(S0_INT) Interrupt Mask</td>
</tr>
</tbody>
</table>
### 4.2 Socket Registers

$Sn_{1\_MR}$ (Socket n-th-th Mode Register) [R/W] [0x4000+0x0n00] [0x00] \(^2\)

This register sets up socket option or protocol type for each socket.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
</table>
| 7   | MULTI  | Multicasting  
\> 0 : disable Multicasting 
\> 1 : enable Multicasting 
\> It is applied only in case of UDP. 
\> For using multicasting, write multicast group address to Socket n-th Destination IP and multicast group port number to Socket n-th Destination Port Register, before OPEN command. |
| 6   | MF     | MAC Filter  
\> 0 : Disable MAC filter 
\> 1 : Enable MAC filter 
\> It is used in MACRAW (P3–P0: “0100”). 
\> When this bit is set as ‘1’, W5200 can receive packet that is belong in itself or broadcasting. When this bit is set as ‘0’, W5200 can receive all packets on Ethernet. When using the hybrid TCP/IP stack, it is recommended to be set as ‘1’ for reducing the receiving overhead of host. |
| 5   | ND/MC  | Use No Delayed ACK  
\> 0 : Disable No Delayed ACK option 
\> 1 : Enable No Delayed ACK option, 
\> This only applies to TCP case (P3–P0: “0001”) If this bit is set as ‘1’, ACK packet is immediately transmitted after receiving data packet from a peer. If this bit is cleared, ACK packet is transmitted according to internal timeout mechanism. 
\> Multicast 
\> 0 : using IGMP version 2 
\> 1 : using IGMP version 1 
\> This bit is valid when MULTI bit is enabled and UDP mode is used (P3–P0 : “0010”). In addition, multicast can be used to send out the version number in IGMP messages such as Join/Leave/Report to multicast-group |

\(^{1}\)n is Socket n-th number (0, 1, 2, 3, 4, 5, 6, 7).
\(^{2}\) [Read/Write] [address of socket 0, address of socket 1, address of socket 2, address of socket 3, address of socket 4, address of socket 5, address of socket 6, address of socket 7] [Reset value]
<table>
<thead>
<tr>
<th>4</th>
<th>Reserved</th>
<th>Reserved</th>
</tr>
</thead>
</table>
| 3 | P3 | **Protocol**
Sets up corresponding socket as TCP, UDP, or IP RAW mode |
| 2 | P2 |
| 1 | P1 |
| 0 | P0 |

*In case of socket 0, MACRAW and PPPoE mode exist.*

<table>
<thead>
<tr>
<th>P</th>
<th>P</th>
<th>P</th>
<th>P</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>2</td>
<td>1</td>
<td>0</td>
<td>0 0 0 0 Closed</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>TCP</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>UDP</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>IPRAW</td>
</tr>
</tbody>
</table>

S0_MR_MACRAW and S0_MR_PPPoE are valid only in SOCKET 0.

S0_MR_PPPoE is temporarily used for PPPoE server connection/Termination. After connection is established, it can be utilized as another protocol.
Sn_CR (Socket n-th Command Register) [R/W] [0x4001+0x0n00] [0x00]

This is used to set the command for Socket n-th such as OPEN, CLOSE, CONNECT, LISTEN, SEND, and RECEIVE. After W5200 identifies the command, the Sn_CR register is automatically cleared to 0x00. Even though Sn_CR is cleared to 0x00, the command is still being processed. To verify whether the command is completed or not, please check the Sn_IR or Sn_SR registers.

<table>
<thead>
<tr>
<th>Value</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x01</td>
<td>OPEN</td>
<td>Socket n-th is initialized and opened according to the protocol selected in Sn_MR (P3:P0). The table below shows the value of Sn_SR corresponding to Sn_MR.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
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<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| 0x02  | LISTEN | This is valid only in TCP mode (Sn_MR(P3:P0) = Sn_MR_TCP). In this mode, the Socket n-th is configured as a TCP server which is waiting for connection-request (SYN packet) from any “TCP CLIENT”. The Sn_SR register changes the state from SOCK_INIT to SOCKET_LISTEN. When a client’s connection request is successfully established, the Sn_SR changes from SOCK_LISTEN to SOCK_ESTABLISHED and the Sn_IR(0) becomes ‘1’. On the other hand, Sn_IR(3) is set as ‘1’ and Sn_SR changes to SOCK_CLOSED during a connection failure (SYN/ACK packet failed to transfer)  
|       |        | cf> If the destination port of the TCP Client does not exist during a connection request, W5200 will transmit a RST packet and Sn_SR is unchanged. |
| 0x04  | CONNECT| This mode is only valid in TCP mode and operates the Socket n-th as a TCP client. A connect-request (SYN packet) is sent to the TCP server by connecting to the IP address and port stored in destination address and port registers (Sn_DIPR0 and Sn_DPORT0)  
|       |        | When a client’s connection request is successfully established, the Sn_SR register is changed to SOCK_ESTABLISHED and the Sn_IR(0) becomes ‘1’. In the following cases, the connect-request fails. When a ARPTO occurs (Sn_IR(s)=’1’) because the Destination Hardware Address is not acquired through the ARP process |

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### When a SYN/ACK packet is not received and TCPTO(Sn_IR(3)) is '1'
- When a RST packet is received instead of a SYN/ACK packet
- Above three cases, Sn_SR is changed to SOCK_CLOSED.

| 0x08  | DISCON | Only valid in TCP mode
Regardless of “TCP SERVER” or “TCP CLIENT”, this disconnect command processes the
- **Active close**: it transmits disconnect-request (FIN packet) to the connected peer
- **Passive close**: When FIN packet is received from peer, a FIN packet is replied back to the peer
when FIN/ACK packet is received, Sn_SR is changed to SOCK_CLOSED.
When a disconnect request is not received, TCPTO occurs (Sn_IR(3)='1') and Sn_SR is changed to SOCK_CLOSED.
cf> If CLOSE is used instead of DISCON, only Sn_SR is changed to SOCK_CLOSED without disconnect-process(disconnect-request). If a RST packet is received from a peer during communication, Sn_SR is unconditionally changed to SOCK_CLOSED.

| 0x10  | CLOSE  | Closes Socket n-th.
Sn_SR is changed to SOCK_CLOSED.

| 0x20  | SEND   | SEND transmits all the data buffered in the TX memory. For more details, please refer to Socket n-th TX Free Size Register (Sn_TX_FSR0), Socket n-th TX Write Pointer Register (Sn_TX_WR0), and Socket n-th TX Read Pointer Register (Sn_TX_RD0).

| 0x21  | SEND_MAC | Used in UDP mode only
The basic operation is the same as SEND. Normally SEND operation needs Destination Hardware Address which can be retrieved by the ARP (Address Resolution Protocol) process. SEND_MAC uses Socket n-th Destination Hardware Address (Sn_DHAR0) that is chosen by the user without going through the ARP process.

| 0x22  | SEND_KEEP | Used in TCP mode
It checks the connection status by sending 1byte data. If the connection has no response from peers or is terminated, the Timeout interrupt will occur.

| 0x40  | RECV    | RECV processes the data received by using a RX read pointer register (Sn_RX_RD).
For more detail, please refer to 5.2.1.1 SERVER mode Receiving Process with Socket n-th RX Received Size Register (Sn_RX_RSR0), Socket n-th RX Write Pointer Register (Sn_RX_WR), and Socket n-th RX Read Pointer...
Below commands are only valid for SOCKET 0 and S0_MR(P3:P0) = S0_MR_PPPoE. For more detail refer to the “How to use ADSL”.

<table>
<thead>
<tr>
<th>Value</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x23</td>
<td>PCON</td>
<td>PPPoE connection begins by transmitting PPPoE discovery packet</td>
</tr>
<tr>
<td>0x24</td>
<td>PDISCON</td>
<td>Closes PPPoE connection</td>
</tr>
<tr>
<td>0x25</td>
<td>PCR</td>
<td>In each phase, it transmits REQ message.</td>
</tr>
<tr>
<td>0x26</td>
<td>PCN</td>
<td>In each phase, it transmits NAK message.</td>
</tr>
<tr>
<td>0x27</td>
<td>PCJ</td>
<td>In each phase, it transmits REJECT message.</td>
</tr>
</tbody>
</table>
Sn_IR (Socket n-th Interrupt Register) [R] [0x4002+0x0n00] [0x00]

Sn_IR register provides information such as the type of interrupt (establishment, termination, receiving data, timeout) used in Socket n-th. When an interrupt occurs and the mask bit of Sn_IMR is ‘1’, the interrupt bit of Sn_IR becomes ‘1’.

In order to clear the Sn_IR bit, the host should write the bit as ‘1’. When all the bits of Sn_IR is cleared (‘0’), IR(n) is automatically cleared.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
</table>
| 7   | PRECV  | Sn_IR(PRECV) Interrupt Mask
      |        | Valid only in case of 'SOCKET=0' and 'S0_MR(P3:P0)=S0_MR_PPPoE'
      |        | PPP Receive Interrupts when the option which is not supported is received |
| 6   | PFAIL  | Sn_IR(PFAIL) Interrupt Mask
      |        | Valid only in case of 'SOCKET=0' & 'S0_MR(P3:P0)=S0_MR_PPPoE'
      |        | PPP Fail Interrupts when PAP Authentication is failed |
| 5   | PNEXT  | Sn_IR(PNEXT) Interrupt Mask
      |        | Valid only in case of 'SOCKET=0' & 'S0_MR(P3:P0)=S0_MR_PPPoE'
      |        | PPP Next Phase Interrupts when the phase is changed during ADSL connection process |
| 4   | SEND_OK| Sn_IR(SENDOK) Interrupt Mask
      |        | SEND OK Interrupts when the SEND command is completed |
| 3   | TIMEOUT| Sn_IR(TIMEOUT) Interrupt Mask
      |        | TIMEOUT Interrupts when ARP_TO or TCP_TO occurs |
| 2   | RECV   | Sn_IR(RECV) Interrupt Mask
      |        | Receive Interrupts whenever data packet is received from a peer |
| 1   | DISCON | Sn_IR(DISCON) Interrupt Mask
      |        | Disconnect Interrupts when FIN of FIN/ACK packet is received from a peer |
| 0   | CON    | Sn_IR(CON) Interrupt Mask
      |        | Connect Interrupts when a connection is established with a peer |
Sn_SR (Socket n-th Status Register) [R] [0x4003+0x0n00] [0x00]

This register provides the status of Socket n-th. SOCKET status are changed when using the Sn_CR register or during packet transmission/reception. The table below describes the different states of Socket n-th.

<table>
<thead>
<tr>
<th>Value</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>SOCK_CLOSED</td>
<td>It is the status that resource of SOCKETn is released. When DISCON or CLOSE command is performed, or ARP_TO, or TCP_TO occurs, it is changed to SOCK_CLOSED regardless of previous value.</td>
</tr>
<tr>
<td>0x13</td>
<td>SOCK_INIT</td>
<td>It is shown in case that Sn_MR is set as TCP and OPEN commands are given to Sn_CR. It is changed to SOCK_INIT when Sn_MR (P3:P0) is Sn_MR_TCP and OPEN command is performed. It is the initial step of TCP connection establishment. It is possible to perform LISTEN command at the “TCP SERVER” mode and CONNECT command at the “TCP CLIENT”. It is the status that SOCKETn operates as “TCP SERVER” and waits for connect-request (SYN packet) from “TCP CLIENT”.</td>
</tr>
<tr>
<td>0x14</td>
<td>SOCK_LISTEN</td>
<td>Socket n-th operates in TCP Server Mode and waits for a connection-request (SYN packet) from a “TCP CLIENT”. When the LISTEN command is used, the stage changes to SOCK_LISTEN. Once the connection is established, the SOCKET state changes from SOCK_LISTEN to SOCK_ESTABLISHED; however, if the connection fails, TCP_TO occurs (Sn_IR(TIME_OUT) = ‘1’) and the state changes to SOCK_CLOSED.</td>
</tr>
<tr>
<td>0x17</td>
<td>SOCK_ESTABLISHED</td>
<td>It is shown in case that connection is established. It is changed to SOCK_ESTABLISHED when SYN packet from “TCP CLIENT” is successfully processed at the SOCK_LISTEN, or CONNECTS command is successfully performed. At this status, DATA packet can be transferred, that is, SEND or RECV command can be performed.</td>
</tr>
<tr>
<td>0x1C</td>
<td>SOCK_CLOSE_WAIT</td>
<td>It is the status that disconnect-request (FIN packet) is received from the peer As TCP connection is half-closed, it is possible to transfer data packet. In order to complete the TCP disconnection, DISCON command should be performed. For SOCKETn close without disconnection-process, CLOSE command should be just performed.</td>
</tr>
</tbody>
</table>
It is the status that SOCKETn is open as UDP mode. It is changed to SOCK_UDP when Sn_MR(P3:P0) is Sn_MR_UDP and OPEN command is performed. DATA packet can be transferred without connection that is necessary to TCP mode SOCKET.

The socket is opened in IPRAW mode. The SOCKET status is change to SOCK_IPRAW when Sn_MR (P3:P0) is Sn_MR_IPRAW and OPEN command is used. IP Packet can be transferred without a connection similar to the UDP mode.

It is changed to SOCK_MACRAW in case of S0_CR=OPEN and S0_MR (P3:P0)=S0_MR_MACRAW. MACRAW packet (Ethernet frame) can be transferred similar to UDP mode.

It is the status that SOCKET0 is open as PPPoE mode. It is changed to SOCK_PPPoE in case of S0_CR=OPEN and S0_MR (P3:P0)=S0_MR_PPPoE . It is temporarily used at the PPPoE connection.

Below is shown during changing the status.

<table>
<thead>
<tr>
<th>Value</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x15</td>
<td>SOCK_SYNSENT</td>
<td>This status indicates that a connect-request (SYN packet) is sent to a &quot;TCP SERVER&quot;. This status shows changing process from SOCK_INIT to SOCK_ESTABLISHED by CONNECT command. At this status, if connect-accept (SYN/ACK packet) is received from &quot;TCP SERVER&quot;, it is automatically changed to SOCK_ESTABLISHED. If SYN/ACK packet is not received from the &quot;TCP SERVER&quot; before TCPTO occurs (Sn_IR(TIMEOUT)='1'), it is changed to SOCK_CLOSED.</td>
</tr>
<tr>
<td>0x16</td>
<td>SOCK_SYNRECV</td>
<td>This status indicate that a connect-request(SYN packet) is received from a &quot;TCP CLIENT&quot;. It is automatically changed to SOCK_ESTABLISHED when W5200 successfully transmits connect-accept (SYN/ACK packet) to the &quot;TCP CLIENT&quot;. If it is failed, TCPTO occurs (Sn_IR(TIMEOUT)='1'), and it is changed to SOCK_CLOSED</td>
</tr>
<tr>
<td>0x18</td>
<td>SOCK_FIN_WAIT</td>
<td>These status shows that Socket n-th is closed. It is observed in the disconnect-process of active close or passive close. It is changed to SOCK_CLOSED, when disconnect-process is successfully finished or TCPTO occurs (Sn_IR (TIMEOUT) =&quot;1&quot;).</td>
</tr>
<tr>
<td>0x1A</td>
<td>SOCK_CLOSING</td>
<td></td>
</tr>
<tr>
<td>0x1B</td>
<td>SOCK_TIME_WAIT</td>
<td></td>
</tr>
<tr>
<td>0x1D</td>
<td>SOCK_LAST_ACK</td>
<td></td>
</tr>
<tr>
<td>0x01</td>
<td>SOCK_ARP</td>
<td>This status indicates that ARP-request is transmitted in order to acquire destination hardware address. This status</td>
</tr>
</tbody>
</table>
is observed when SEND command is performed at the SOCK_UDP or SOCK_IPRAW, or CONNECT command is performed at the SOCK_INIT.

If hardware address is successfully acquired from destination (when ARP-response is received), it is changed to SOCK_UDP, SOCK_IPRAW or SOCK_SYNSENT. If it’s failed and ARPTO occurs (Sn_IR(TIMEOUT)=’1’), in case of UDP or IPRAW mode it goes back to the previous status (the SOCK_UDP or SOCK_IPRAW), in case of TCP mode it goes to the SOCK_CLOSED.

cf> ARP-process operates at the SOCK_UDP or SOCK_IPRAW when the previous and current values of Sn_DIPR are different. If the previous and current values of Sn_DIPR are same, ARP-process doesn’t operate because the destination hardware address is already acquired.

Figure 6 Socket Status Transition
**Sn_PORT (Socket n-th Source Port Register) [R/W] [0x4004+0x0n00-0x4005+0x0n00] [0x0000]**

This register sets the Source Port number for each Socket when using TCP or UDP mode, and the set-up needs to be made before executing the OPEN command.

**Ex)** In case of Socket 0 Port = 5000(0x1388), configure as below,

<table>
<thead>
<tr>
<th>0x4004</th>
<th>0x4005</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x13</td>
<td>0x88</td>
</tr>
</tbody>
</table>

**Sn_DHAR (Socket n-th Destination Hardware Address Register) [R/W] [0x4006+0x0n00-0x400B+0x0n00] [0xFFFFFFFFFFFF]**

It sets or is set as destination hardware address of Socket n-th. Also, if SOCKET 0 is used for PPPoE mode, S0_DHAR sets as PPPoE server hardware an address that is already known.

When using SEND_MAC command at the UDP or IPRAW mode, it sets the destination hardware address of Socket n-th. At the TCP, UDP and IPRAW mode, Sn_DHAR is set as destination hardware address that is acquired by ARP-process of CONNECT or SEND command. The host can acquire the destination hardware address through Sn_DHAR after successfully performing CONNET or SEND command.

When using PPPoE-process of W5200, PPPoE server hardware address is not required to be set. However, even if PPPoE-process of W5200 is not used, but implemented by yourself with MACRAW mode, in order to transmit or receive the PPPoE packet, PPPoE server hardware address(acquired by your PPPoE-process), PPPoE server IP address, and PPP session ID should be set, and MR(PPPoE) also should be set as ‘1’.

S0_DHAR sets the PPPoE server hardware address before the OPEN command. PPPoE server hardware address which is set by S0_DHAR is applied to PDHAR after performing the OPEN command. The configured PPPoE information is internally valid even after the CLOSE command.

**Ex)** In case of Socket 0 Destination Hardware address = 08.DC.00.01.02.10, configuration is as below,

<table>
<thead>
<tr>
<th>0x4006</th>
<th>0x4007</th>
<th>0x4008</th>
<th>0x4009</th>
<th>0x400A</th>
<th>0x400B</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0xDC</td>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>0x0A</td>
</tr>
</tbody>
</table>

**Sn_DIPR (Socket n-th Destination IP Address Register) [R/W] [0x400C+0x0n00-0x400F+0x0n00] [0x00000000]**

It sets or is set as destination IP address of Socket n-th. If SOCKET0 is used as PPPoE mode, S0_DIPR sets PPPoE server IP address that is already known. It is valid only in TCP, UDP, IPRAW or PPPoE mode, but ignored in MACRAW mode. At the TCP mode, when operating as “TCP CLIENT” it sets as IP address of "TCP SERVER" before performing CONNECT command and when operating as "TCP SERVER", it is internally set as IP address of "TCP CLIENT" after successfully establishing connection.
At the UDP or IPRAW mode, Sn_DIPR sets as destination IP address to be used for transmitting UDP or IPRAW DATA packet before performing SEND or SEND_MAC command.

Ex) In case of Socket 0 Destination IP address = 192.168.0.11, configure as below.

<table>
<thead>
<tr>
<th>0x400C</th>
<th>0x040D</th>
<th>0x400E</th>
<th>0x040F</th>
</tr>
</thead>
<tbody>
<tr>
<td>192 (0xC0)</td>
<td>168 (0xA8)</td>
<td>0 (0x00)</td>
<td>11 (0x0B)</td>
</tr>
</tbody>
</table>

Sn_DPORT (Socket n-th Destination Port Register) [R/W] [0x4010+0x0n00-0x4011+0x0n00] [0x00]

The destination port number is set in the Sn_DPORT of Socket n-th. If SOCKET 0 is used as PPPoE mode, S0_DPORT0 sets PPP session ID that is already known. It is valid only in TCP, UDP or PPPoE mode, and ignored in other modes.

At the TCP mode, when operating as "TCP CLIENT", it listens for the port number of the "TCP SERVER" before performing the CONNECT command.

At the UDP mode, the destination port number is set in the Sn_DPORT to be used for transmitting UDP DATA packets before performing SEND or SEND_MAC command.

At the PPPoE mode, the PPP session ID that is already known is set in the S0_DPORT. PPP session ID (set by S0_DPORT0) is applied to PSIDR after performing the OPEN command.

Ex) In case of Socket 0 Destination Port = 5000(0x1388), configure as below,

<table>
<thead>
<tr>
<th>0x4010</th>
<th>0x4011</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x13</td>
<td>0x88</td>
</tr>
</tbody>
</table>

Sn_MSS (Socket n-th Maximum Segment Size Register) [R/W] [0x4012+0x0n00-0x4013+0x0n00] [0x0000]

This register is used for MSS (Maximum Segment Size) of TCP, and the register displays MSS set by the other party when TCP is activated in Passive Mode. It just supports TCP or UDP mode. When using PPPoE (MR(PPPoE)=‘1’), the MTU of TCP or UDP mode is assigned in the range of MTU of PPPoE.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Default (MR(PPPoE)=‘0’)</th>
<th>PPPoE (MR(PPPoE)=‘1’)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Default MTU</td>
<td>Range</td>
</tr>
<tr>
<td>TCP</td>
<td>1460</td>
<td>1 - 1460</td>
</tr>
<tr>
<td>UDP</td>
<td>1472</td>
<td>1 - 1472</td>
</tr>
<tr>
<td>IPRAW</td>
<td>1480</td>
<td>1472</td>
</tr>
<tr>
<td>MACRAW</td>
<td></td>
<td>1514</td>
</tr>
</tbody>
</table>

At the IPRAW or MACRAW, MTU is not processed internally, but default MTU is used. Therefore, when transmitting the data bigger than default MTU, the host should manually divide the data into the unit of default MTU.

At the TCP or UDP mode, if transmitting data is bigger than MTU, W5200 automatically divides
the data into the unit of MTU. MTU is called as MSS at the TCP mode. By selecting from Host-Written-Value and peer’s MSS, MSS is set as smaller value through TCP connection process.

Ex) In case of Socket 0 MSS = 1460(0x05B4), configure as below,

<table>
<thead>
<tr>
<th>0x4012</th>
<th>0x4013</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x05</td>
<td>0xB4</td>
</tr>
</tbody>
</table>

**SnPROTO** (Socket n-th IP Protocol Register) [R/W] [0x4014+0x0n00] [0x00]
It is a 1 byte register that sets the protocol number field of the IP header at the IP layer. It is valid only in IPRAW mode, and ignored in other modes. SnPROTO is set before OPEN command. When Socket n-th is opened in IPRAW mode, it transmits and receives the data of the protocol number set in SnPROTO. SnPROTO can be assigned in the range of 0x00 ~ 0xFF, but W5200 does not support TCP(0x06) and UDP(0x11) protocol number
Protocol number is defined in IANA(Internet assigned numbers authority). For the detail, refer to online document ([http://www.iana.org/assignments/protocol-numbers](http://www.iana.org/assignments/protocol-numbers)).

Ex) Internet Control Message Protocol (ICMP) = 0x01, Internet Group Management Protocol = 0x02

**SnTOS** (Socket n-th IP Type Of Service Register) [R/W] [0x4015+0x0n00] [0x00]
It sets the TOS(Type of Service) field of the IP header at the IP layer. It should be set before the OPEN command. Refer to [http://www.iana.org/assignments/ip-parameters](http://www.iana.org/assignments/ip-parameters).

**SnTTL** (Socket n-th IP Time To Live Register) [R/W] [0x4016+0x0n00] [0x80]
It sets the TTL(Time To Live) field of the IP header at the IP layer. It should be set before the OPEN command. Refer to [http://www.iana.org/assignments/ip-parameters](http://www.iana.org/assignments/ip-parameters).
Sn_RXMEM_SIZE(Socket n-th RX Memory Size Register) [R/W] [0x401E+0x0n00] [0x02]

It configures the internal RX Memory size of each SOCKET. RX Memory size of each SOCKET is configurable in the size of 1, 2, 4, 8, and 16 Kbytes. 2Kbytes is assigned when reset. Sn_RXMEM_SIZE_SUM(summation of Sn_RXMEM_SIZE) of each SOCKET should be 16KB.

<table>
<thead>
<tr>
<th>Value</th>
<th>Memory size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x01</td>
<td>1KB</td>
</tr>
<tr>
<td>0x02</td>
<td>2KB</td>
</tr>
<tr>
<td>0x04</td>
<td>4KB</td>
</tr>
<tr>
<td>0x08</td>
<td>8KB</td>
</tr>
<tr>
<td>0x0F</td>
<td>16KB</td>
</tr>
</tbody>
</table>

Ex1) SOCKET 0 : 8KB, SOCKET 1 : 2KB

0xFE401E 0xFE411E
0x08 0x02

Ex2) SOCKET 2 : 1KB, SOCKET 3 : 1KB

0xFE421E 0xFE431E
0x01 0x01

Ex3) SOCKET 4 : 1KB, SOCKET 5 : 1KB

0xFE441E 0xFE451E
0x01 0x01

Ex4) SOCKET 6 : 1KB, SOCKET 7 : 1KB

0xFE461E 0xFE471E
0x01 0x01

Sn_TXMEM_SIZE(Socket n-th TX Memory size Register) [R/W][0x401F+0x0n00] [0x02]

It configures the internal TX Memory size of each SOCKET. TX Memory size of each SOCKET is configurable in the size of 1, 2, 4, 8, and 16 Kbytes. 2Kbytes is assigned when reset. Sn_TXMEM_SIZE_SUM(summation of Sn_TXMEM_SIZE) of each SOCKET should be 16KB.

Ex1) SOCKET 0 : 4KB, SOCKET 1 : 1KB

0xFE401F 0xFE411F
0x04 0x01

Ex2) SOCKET 2 : 2KB, SOCKET 3 : 1KB

0xFE421F 0xFE431F
0x02 0x01

Ex3) SOCKET 4 : 2KB, SOCKET 5 : 2KB

0xFE441F 0xFE451F
0x02 0x02

Ex4) SOCKET 6 : 2KB, SOCKET 7 : 2KB

0xFE461F 0xFE471F
0x02 0x02
Sn_TX_FSR (Socket n-th TX Free Size Register) [R] [0x4020+0x0n00-0x4021+0x0n00] [0x0800]
It notifies the available size of the internal TX memory (the byte size of transmittable data) of Socket n-th. The host can’t write data as a size bigger than Sn_TX_FSR. Therefore, be sure to check Sn_TX_FSR before transmitting data, and if your data size is smaller than or the same as Sn_TX_FSR, transmit the data with SEND or SEND_MAC command after copying the data.
At the TCP mode, if the peer checks the transmitted DATA packet (if DATA/ACK packet is received from the peer), Sn_TX_FSR is automatically increased by the size of that transmitted DATA packet. At the other modes, when Sn_IR(SENDOK) is ‘1’, Sn_TX_FSR is automatically increased by the size of the transmitted data. When checking this register, user should read upper byte(0x4020, 0x4120, 0x4220, 0x4320, 0x4420, 0x4520, 0x4620, 0x4720) first and lower byte(0x4021, 0x4121, 0x4221, 0x4321, 0x4421, 0x4521, 0x4621, 0x4721) later to get the correct value.

Ex) In case of 2048(0x0800) in S0_TX_FSR,

<table>
<thead>
<tr>
<th>0x4020</th>
<th>0x4021</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>

Sn_TX_RD (Socket n-th TX Read Pointer Register) [R] [0x4022+0x0n00-0x4023+0x0n00] [0x0000]
This register shows the address of the last transmission finishing in the TX memory. With the SEND command of Socket n-th Command Register, it transmits data from the current Sn_TX_RD to the Sn_TX_WR and automatically updates after transmission is finished. Therefore, after transmission is finished, Sn_TX_RD and Sn_TX_WR will have the same value. When reading this register, user should read upper byte (0x4022, 0x4122, 0x4222, 0x4322, 0x4422, 0x4522, 0x4622, 0x4722) first, and lower byte (0x4023, 0x4123, 0x4223, 0x4323, 0x4423, 0x4523, 0x4623, 0x4723) later to get the correct value.

Sn_TX_WR (Socket n-th TX Write Pointer Register) [R/W] [0x4024+0x0n00-0x4025+0x0n00] [0x0000]
This register offers the location information to write the transmission data. When reading this register, user should read upper byte (0x4024, 0x4124, 0x4224, 0x4324, 0x4424, 0x4524, 0x4624, 0x4724) first, and lower byte (0x4025, 0x4125, 0x4225, 0x4325, 0x4425, 0x4525, 0x4625, 0x4725) later to get the correct value.
Caution: This register value is changed after the send command is successfully executed to Sn_CR.

Ex) In case of 2048(0x0800) in S0_TX_WR,

<table>
<thead>
<tr>
<th>0x4024</th>
<th>0x4025</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>
But this value itself is not the physical address to read. So, the physical address should be calculated as follow.

1. Socket n-th TX Base Address (hereafter we'll call $gSn_{-}TX\_BASE$) and Socket n-th TX Mask Address (hereafter we'll call $gSn_{-}TX\_MASK$) are calculated on TMSR value. Refer to the pseudo code of the Initialization if detail is needed.

2. The bitwise-AND operation of two values, $Sn\_TX\_WR$ and $gSn_{-}TX\_MASK$ give result to the offset address (hereafter we'll call $get\_offset$) in TX memory range of the socket.

3. Two values $get\_offset$ and $gSn_{-}TX\_BASE$ are added together to give result to the physical address (hereafter, we'll call $get\_start\_address$).

Now, write the transmission data to $get\_start\_address$ as large as you want. (* There's a case that it exceeds the TX memory upper-bound of the socket while writing. In this case, write
the transmission data to the upper-bound, and change the physical address to the 
gSn_TX_BASE. Next, write the rest of the transmission data.) After that, be sure to increase 
the Sn_TX_WR value as much as the data size that indicates the size of writing data. Finally, 
give SEND command to Sn_CR(Socket n-th Command Register).

Refer to the pseudo code of the transmission part on TCP Server mode if detail is needed.

Sn_RX_RSR (SOCKET n-th Received Size Register) [R] [0x4026+0x0n00-0x4027+0x0n00] 
[0x0000]
It informs the user of the byte size of the received data in Internal RX Memory of Socket n-th. 
As this value is internally calculated with the values of Sn_RX_RD and Sn_RX_WR, it is 
automatically changed by RECV command of Socket n-th Command Register (Sn_CR) and 
receives data from the remote peer. When reading this register, user should read upper 
byte(0x4026, 0x4126, 0x4226, 0x4326, 0x4426, 0x4526, 0x4626, 0x4726) first, and lower 
byte(0x4027, 0x4127, 0x4227, 0x4327, 0x4427, 0x4527, 0x4627, 0x4727) later to get the 
correct value.

Ex) In case of 2048(0x0800) in S0_RX_RSR,

<table>
<thead>
<tr>
<th>0x4026</th>
<th>0x4027</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>

The total size of this value can be decided according to the value of RX Memory Size Register.

Sn_RX_RD (Socket n-th RX Read Pointer Register) [R/W] [0x4028+0x0n00-0x4029+0x0n00] 
[0x0000]
This register offers the location information to read the receiving data. When reading this 
register, user should read upper byte (0x4028, 0x4128, 0x4228, 0x4328, 0x4428, 0x4528, 
0x4628, 0x4728) first, and lower byte (0x4029, 0x4129, 0x4229, 0x4329, 0x4429, 0x4529, 
0x4629, 0x4729) later to get the correct value. It has a random value as its initial value.
Caution: This register value is changed after the SEND command is successfully executed to 
Sn_CR.

Ex) In case of 2048(0x0800) in S0_RX_RD,

<table>
<thead>
<tr>
<th>0x4028</th>
<th>0x4029</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>

But this value itself is not the physical address to read. So, the physical address should be 
calculated as follow.
1. Socket n-th RX Base Address (hereafter we'll call gSn_RX_BASE) and Socket n-th RX 
Mask Address (hereafter we'll call gSn_RX_MASK) are calculated on RMSR value. Refer 
to the pseudo code of the 5.1 Initialization if the detail is needed.
2. The bitwise-AND operation of two values, Sn_RX_RD and gSn_RX_MASK give result the 
offset address(hereafter we'll call get_offset), in RX memory range of the socket.
3. Two values get_offset and gSn_RX_BASE are added together to give result the
physical address (hereafter, we'll call get_start_address).

Sn_RX_WR (Socket n-th RX Write Pointer Register)[R/W][0xFE402A + 0x0n00] -  
(0xFE402B + 0x0n00)][0x0000]

This register offers the location information to write the receive data. When reading this  
register, the user should read upper bytes (0x402A, 0x412A, 0x422A, 0x432A, 0x442A, 0x452A,  
0x462A, 0x472A) first and lower bytes (0x402B, 0x412B, 0x422B, 0x432B, 0x442B, 0x452B,  
0x462B, 0x472B) later to get the correct value.

Ex) In case of 2048(0x0800) in S0_RX_WR,

<table>
<thead>
<tr>
<th>0x402A</th>
<th>0x402B</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x00</td>
</tr>
</tbody>
</table>

Sn_IMR (Socket n-th Interrupt Mask Register)[R/W][0x402C+0x0n00][0xFF]

It configures the interrupt of Socket n-th so as to notify to the host. Interrupt mask bit of  
Sn_IMR corresponds to interrupt bit of Sn_IR. If interrupt occurs in any SOCKET and the bit is  
set as ‘1’, its corresponding bit of Sn_IR is set as ‘1’. When the bits of Sn_IMR and Sn_IR are  
‘1’, IR(n) becomes ‘1’. At this time, if IMR(n) is ‘1’, the interrupt is issued to the host. (‘nINT’  
signal is asserted low)

<table>
<thead>
<tr>
<th>Bit</th>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
</table>
| 7   | PRECV  | Sn_IR(PRECV) Interrupt Mask  
Valid only in case of ‘SOCKET = 0’ & ‘S0_MR(P3:P0) = S0_MR_PPPoE’ |
| 6   | PFAIL  | Sn_IR(PFAIL) Interrupt Mask  
Valid only in case of ‘SOCKET = 0’ & ‘S0_MR(P3:P0) = S0_MR_PPPoE’ |
| 5   | PNEXT  | Sn_IR(PNEXT) Interrupt Mask  
Valid only in case of ‘SOCKET = 0’ & ‘S0_MR(P3:P0) = S0_MR_PPPoE’ |
| 4   | SENDOK | Sn_IR(SENDOK) Interrupt Mask |
| 3   | TIMEOUT| Sn_IR(TIMEOUT) Interrupt Mask |
| 2   | RECV   | Sn_IR(RECV) Interrupt Mask |
| 1   | DISCON | Sn_IR(DISCON) Interrupt Mask |
| 0   | CON    | Sn_IR(CON) Interrupt Mask |
Sn_FRAG (Socket n-th Fragment Register) [R/W][0x402D+0x0n00-0x402E+0x0n100][0x4000]

It sets the Fragment field of the IP header at the IP layer. W5200 does not support the packet fragment at the IP layer. Even though Sn_FRAG is configured, IP data is not fragmented, and not recommended either. It should be configured before performing OPEN command.

Ex) Sn_FRAG0 = 0x4000 (Don’t Fragment)

<table>
<thead>
<tr>
<th>0x402D</th>
<th>0x402E</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x40</td>
<td>0x00</td>
</tr>
</tbody>
</table>
5 Functional Descriptions

By setting some register and memory operation, W5200 provides internet connectivity. This chapter describes how it can be operated.

5.1 Initialization

Basic Setting

For the W5200 operation, select and utilize appropriate registers shown below.

1. Mode Register (MR)
2. Interrupt Mask Register (IMR)
3. Retry Time-value Register (RTR)
4. Retry Count Register (RCR)

For more information of above registers, refer to the “Register Descriptions.”

Setting network information

Basic network information setting for communication:
It must be set the basic network information.

1. SHAR(Source Hardware Address Register)
   It is prescribed that the source hardware addresses, which is set by SHAR, use unique hardware addresses (Ethernet MAC address) in the Ethernet MAC layer. The IEEE manages the MAC address allocation. The manufacturer which produces the network device allocates the MAC address to product.
   Details on MAC address allocation refer to the website as below.

2. GAR(Gateway Address Register)

3. SUBR(Subnet Mask Register)

4. SIPR(Source IP Address Register)
This stage sets the socket tx/rx memory information. The base address and mask address of each socket are fixed and saved in this stage.

In case of, assign 2KB rx, tx memory per SOCKET
{
  gS0_RX_BASE = 0x0000(Chip base address) + 0xC000(Internal RX buffer address); // Set base address of RX memory for SOCKET 0
  Sn_RXMEM_SIZE(ch) = (uint8 *) 2; // Assign 2K rx memory per SOCKET
  gS0_RX_MASK = 2K - 1; // 0x07FF, for getting offset address within assigned SOCKET 0 RX memory
  gS1_RX_BASE = gS0_RX_BASE + (gS0_RX_MASK + 1);
  gS1_RX_MASK = 2K - 1;
  gS2_RX_BASE = gS1_RX_BASE + (gS1_RX_MASK + 1);
  gS2_RX_MASK = 2K - 1;
  gS3_RX_BASE = gS2_RX_BASE + (gS2_RX_MASK + 1);
  gS3_RX_MASK = 2K - 1;
  gS4_RX_BASE = gS3_RX_BASE + (gS3_RX_MASK + 1);
  gS4_RX_MASK = 2K - 1;
  gS5_RX_BASE = gS4_RX_BASE + (gS4_RX_MASK + 1);
  gS5_RX_MASK = 2K - 1;
  gS6_RX_BASE = gS5_RX_BASE + (gS5_RX_MASK + 1);
  gS6_RX_MASK = 2K - 1;
  gS7_RX_BASE = gS6_RX_BASE + (gS6_RX_MASK + 1);
  gS7_RX_MASK = 2K - 1;

  gS0_TX_BASE = 0x0000(Chip base address) + 0x8000(Internal TX buffer address); // Set base address of TX memory for SOCKET 0
  Sn_TXMEM_SIZE(ch) = (uint8 *) 2; // Assign 2K rx memory per SOCKET
  gS0_TX_MASK = 2K - 1;
  /* Same method, set gS1_TX_BASE, gS1_TX_MASK, gS2_TX_BASE, gS2_TX_MASK,
   gS3_TX_BASE, gS3_TX_MASK, gS4_TX_BASE, gS4_TX_MASK, gS5_TX_BASE, gS5_TX_MASK,
   gS6_TX_BASE, gS6_TX_MASK, gS7_TX_BASE, gS7_TX_MASK */
}
Figure 8 Allocation Internal TX/RX memory of Socket n-th

(a) TX memory

<table>
<thead>
<tr>
<th>Socket 7</th>
<th>0xB800</th>
<th>gS7_TX_BASE = 0xB800</th>
<th>gS7_TX_MASK = 0x07FF</th>
</tr>
</thead>
<tbody>
<tr>
<td>Socket 6</td>
<td>0xB000</td>
<td>gS6_TX_BASE = 0xB000</td>
<td>gS6_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 5</td>
<td>0xA800</td>
<td>gS5_TX_BASE = 0xA800</td>
<td>gS5_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 4</td>
<td>0xA000</td>
<td>gS4_TX_BASE = 0xA000</td>
<td>gS4_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 3</td>
<td>0x9800</td>
<td>gS3_TX_BASE = 0x9800</td>
<td>gS3_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 2</td>
<td>0x9000</td>
<td>gS2_TX_BASE = 0x9000</td>
<td>gS2_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 1</td>
<td>0x8800</td>
<td>gS1_TX_BASE = 0x8800</td>
<td>gS1_TX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 0</td>
<td>0x8000</td>
<td>gS0_TX_BASE = 0x8000</td>
<td>gS0_TX_MASK = 0x07FF</td>
</tr>
</tbody>
</table>

(b) RX memory

<table>
<thead>
<tr>
<th>Socket 7</th>
<th>0xF800</th>
<th>gS7_RX_BASE = 0xF800</th>
<th>gS7_RX_MASK = 0x07FF</th>
</tr>
</thead>
<tbody>
<tr>
<td>Socket 6</td>
<td>0xF000</td>
<td>gS6_RX_BASE = 0xF000</td>
<td>gS6_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 5</td>
<td>0xE800</td>
<td>gS5_RX_BASE = 0xE800</td>
<td>gS5_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 4</td>
<td>0xE000</td>
<td>gS4_RX_BASE = 0xE000</td>
<td>gS4_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 3</td>
<td>0xD800</td>
<td>gS3_RX_BASE = 0xD800</td>
<td>gS3_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 2</td>
<td>0xD000</td>
<td>gS2_RX_BASE = 0xD000</td>
<td>gS2_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 1</td>
<td>0xC800</td>
<td>gS1_RX_BASE = 0xC800</td>
<td>gS1_RX_MASK = 0x07FF</td>
</tr>
<tr>
<td>Socket 0</td>
<td>0xC000</td>
<td>gS0_RX_BASE = 0xC000</td>
<td>gS0_RX_MASK = 0x07FF</td>
</tr>
</tbody>
</table>
5.2 Data Communications

After the initialization process, W5200 can transmit and receive the data with others by ‘open’ the SOCKET of TCP, UDP, IPRAW, and MACRAW mode. The W5200 supports the independently and simultaneously usable 8 SOCKETS. In this section, the communication method for each mode will be introduced.

5.2.1 TCP

The TCP is a connection-oriented protocol. The TCP make the connection SOCKET by using its own IP address, port number and destination IP address, port number. Then transmits and receives the data by using this SOCKET.

Methods of making the connection to SOCKET are “TCP SERVER” and “TCP CLIENT”. It is divided by transmitting the connect-request (SYN packet).

The “TCP SERVER” listens to the connect-request from the “TCP CLIENT”, and makes connection SOCKET by accepting the transmitted connect-request (Passive-open).

The “TCP CLIENT” transmits the connect-request first to “TCP SERVER” to make the connection (Active-open).

![Figure 9 TCP SERVER and TCP CLIENT](image)
5.2.1.1 TCP SERVER

Figure 10 TCP SERVER Operation Flow

SOCKET Initialization

SOCKET initialization is required for TCP data communication. The initialization is opening the SOCKET. The SOCKET opening process selects one SOCKET from 8 SOCKETS of the W5200, and sets the protocol mode (Sn_MR) and Sn_PORT0 which is source port number (Listen port number in “TCP SERVER”) in the selected SOCKET, and then executes OPEN command. After the OPEN command, if the status of Sn_SR is changed to SOCK_INIT, the SOCKET initialization process is completed. The SOCKET initialization process is identically applied in “TCP SERVER” and “TCP CLIENT.” The Initialization process of Socket n-th in TCP mode is shown below.
{  
START:  
Sn_MR = 0x01;  // sets TCP mode  
Sn_PORT0 = source_port;  // sets source port number  
Sn_CR = OPEN;  // sets OPEN command  
/* wait until Sn_SR is changed to SOCK_INIT */  
if (Sn_SR != SOCK_INIT) Sn_CR = CLOSE; goto START; 
} 

LISTEN 
Run as “TCP SERVER” by LISTEN command.  
{  
/* listen SOCKET */  
Sn_CR = LISTEN;  
/* wait until Sn_SR is changed to SOCK_LISTEN */  
if (Sn_SR != SOCK_LISTEN) Sn_CR = CLOSE; goto START; 
} 

ESTABLISHMENT 
When the status of Sn_SR is SOCK_LISTEN, if it receives a SYN packet, the status of Sn_SR is changed to SOCK_SYNRECV and transmits the SYN/ACK packet. After that, the Socket n-th makes a connection. After it makes the connection of Socket n-th, it enables the data communication. There are two methods to confirm the connection of Socket n-th. 

First method :  
{  
if (Sn_IR(CON) == ‘1’) Sn_IR(CON) = ‘1’; goto ESTABLISHED stage;  
/* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to IR, IMR Sn.IMR and Sn.IR. */  
} 

Second method :  
{  
if (Sn_SR == SOCK_ESTABLISHED) goto ESTABLISHED stage;  
}
CONFIRMATION: Check received data

First Method:

\[
\begin{align*}
\text{if } (\text{Sn IR(RECV)} \equiv '1') \text{ Sn IR(RECV)} = '1'; & \text{goto Receiving Process stage;} \\
& /* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to IR, IMR Sn IMR and Sn IR. */
\end{align*}
\]

Second Method:

\[
\begin{align*}
\text{if } (\text{Sn RX RSR0} \neq 0x0000) & \text{goto Receiving Process stage;}
\end{align*}
\]

The First method: set the Sn IR(RECV) to ‘1’ whenever you receive a DATA packet. If the host receives the next DATA packet without setting the Sn IR(RECV) as ‘1’ in the prior DATA packet, it cannot recognize the Sn IR(RECV) of the next DATA packet. This is due to the prior Sn IR(RECV) and next Sn IR(RECV) being overlapped. So this method is not recommended if the host cannot perfectly process the DATA packets of each Sn IR(RECV).

ESTABLISHMENT: Receiving process

In this process, it processes the TCP data which was received in the Internal RX memory. At the TCP mode, the W5200 cannot receive the data if the size of received data is larger than the RX memory free size of Socket n-th. If the prior stated condition is happened, the W5200 holds on to the connection (pauses), and waits until the RX memory’s free size is larger than the size of the received data.

\[
\begin{align*}
& /* first, get the received size */ \\
& \text{len} = \text{Sn RX RSR}; & // len is received size \\
& /* calculate offset address */ \\
& \text{src mask} = \text{Sn RX RD & gSn RX MASK}; & // src mask is offset address \\
& /* calculate start address(physical address) */ \\
& \text{src ptr} = \text{gSn RX BASE} + \text{src mask}; & // src ptr is physical start address \\
& /* if overflow SOCKET RX memory */ \\
& \text{If}((\text{src mask + len}) > (\text{gSn RX MASK + 1})) \\
& \{
& /* copy upper_size bytes of source_ptr to destination_address */ \\
& \text{upper size} = (\text{gSn RX MASK + 1}) - \text{src mask}; \\
& \text{memcpy}(\text{src ptr}, \text{dst ptr}, \text{upper size}); \\
\end{align*}
\]
ESTABLISHMENT: Check send data / Send process

The size of the transmit data cannot be larger than assigned internal TX memory of Socket n-th. If the size of transmit data is larger than configured MSS, it is divided by size of MSS and transmits. To transmit the next data, user must check the completion of prior SEND command. An error may occur if the SEND command executes before completion of prior SEND command. The larger the data size, the more time to complete the SEND command. So the user should properly divide the data to transmit. To check the completion of the SEND command, it should be check that the send data length is equal with the actual sent data length. The actual sent data length is calculated by the difference of the Sn_TX_RD before and after performing the SEND command. If the actual sent data is less than the send data length, the SEND command is retried for sending the left data. The send process is therefore completed the SEND when the sum of the actual sent data is equal the send data length. A simple example of the send process is as below
Ex) Send Data Length Size= 10,

1) Execute SEND Command with send data length
2) Calculate the actual sent data length
   If the actual sent data length is 7 (= Sn_TX_RD_after_SEND-Sn_TX_RD_befor_SEND),
   the left Data length= 3
3) Retry SEND Command until the sum of the actual sent data length is same the send data length.

Note: Don’t copy data until the sum of the actual sent data length is the send data length.
{  
    /* first, get the free TX memory size */
    FREESIZE:
    freesize = Sn_TX_FSR;
    if (freesize<len) goto FREESIZE;  // len is send size

    /* calculate offset address */
    dst_mask = Sn_TX_WR0 & gSn_TX_MASK;  // dst_mask is offset address
    /* calculate start address(physical address) */
    dst_ptr = gSn_TX_BASE + dst_mask;  // destination_address is physical start address
    /* if overflow SOCKETTX memory */
    if ( (dst_mask + len) > (gSn_TX_MASK + 1) )
    {
        /* copy upper_size bytes of source_addr to destination_address */
        upper_size = (gSn_TX_MASK + 1) - dst_mask;
        memcpy(src_addr, dst_ptr, upper_size);
        /* update source_addr*/
        source_addr += upper_size;
        /* copy left_size bytes of source_addr to gSn_TX_BASE */
        left_size = len - upper_size;
        memcpy(source_addr, gSn_TX_BASE, left_size);
    }
    else
    {
        /* copy len bytes of source_addr to destination_address */
        memcpy(source_addr, dst_ptr, len);
    }

    /* increase Sn_TX_WR as length of len */
    Sn_TX_WR0 += send_size;
    /* set SEND command */
    Sn_CR = SEND;
    /* return real packet size */
    return (read_ptr_after_send - read_ptr_befor_send)
    /* if return value is not equal len (len is send size),
    retry send left data without copying data*/
}
ESTABLISHMENT : Check disconnect-request (FIN packet)

Check if the Disconnect-request (FIN packet) has been received. User can confirm the reception of FIN packet as below.

First method:
```
if (Sn_IR(DISCON) == '1') Sn_IR(DISCON)='1'; goto CLOSED stage;
/* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to IR, IMR Sn.IMR and Sn_IR. */
```

Second method:
```
if (Sn_SR == SOCK_CLOSE_WAIT) goto CLOSED stage;
```

ESTABLISHMENT : Check disconnect / disconnecting process

When the user does not need data communication with others, or receives a FIN packet, disconnect the connection SOCKET.

```
/* set DISCON command */
Sn_CR = DISCON;
```

ESTABLISHMENT : Check closed

Confirm that the Socket n-th is disconnected or closed by DISCON or close command.

First method:
```
if (Sn_IR(DISCON) == '1') goto CLOSED stage;
/* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to IR, IMR Sn.IMR and Sn_IR. */
```

Second method:
```
if (Sn_SR == SOCK_CLOSED) goto CLOSED stage;
```
ESTABLISHMENT: Timeout

The timeout can occur by Connect-request (SYN packet) or its response (SYN/ACK packet), the DATA packet or its response (DATA/ACK packet), the Disconnect-request (FIN packet) or its response (FIN/ACK packet) and transmission all TCP packet. If it cannot transmit the above packets within 'timeout' which is configured at RTR and RCR, the TCP final timeout (TCP_TO) occurs and the state of Sn_SR is set to SOCK_CLOSED. Confirming method of the TCP_TO is as below:

First method:

```c
{  
  if (Sn_IR (TIMEOUT bit) == '1') Sn_IR (TIMEOUT)='1'; goto CLOSED stage;  
  /* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to IR,  
     IMR Sn IMR and Sn IR. */  
}
```

Second method:

```c
{  
  if (Sn_SR == SOCK_CLOSED) goto CLOSED stage;  
}
```

SOCKET Close

It can be used to close the Socket n-th, which disconnected by disconnect-process, or closed by TCP_TO or closed by host’s need without disconnect-process.

```c
{  
  /* clear the remained interrupts of Socket n-th*/  
  Sn_IR = 0xFF;  
  IR(n) = '1';  
  /* set CLOSE command */  
  Sn_CR = CLOSE;  
}
```
5.2.1.2 TCP CLIENT

It is same as TCP server except ‘CONNECT’ state. User can refer to the “5.2.1.1 TCP SERVER”.

CONNECT

Transmit the connect-request (SYN packet) to “TCP SERVER”. It may occurs the timeout such as ARP_TO, TCP_TO when make the “connection SOCKET” with “TCP SERVER”

```c
{
    Sn_DIPR0 = server_ip;  /* set TCP SERVER IP address*/
    Sn_DPORT0 = server_port;  /* set TCP SERVER listen port number*/
    Sn_CR = CONNECT;  /* set CONNECT command */
}
```
5.2.2 UDP

The UDP is a Connection-less protocol. It communicates without “connection SOCKET.” The TCP protocol guarantees reliable data communication, but the UDP protocol uses datagram communication which has no guarantees of data communication. Because the UDP does not use “connection SOCKET,” it can communicate with many other devices with the known host IP address and port number. This is a great advantage; communication with many others by using just one SOCKET, but also it has many problems such as loss of transmitted data, unwanted data received from others, etc. To avoid these problems and guarantee reliability, the host retransmits damaged data or ignores the unwanted data which is received from others. The UDP protocol supports unicast, broadcast, and multicast communication. It follows the below communication flow.

![Figure 12 UDP Operation Flow](image)

5.2.2.1 Unicast and Broadcast

The unicast is one method of UDP communication. It transmits data to one destination at one time. On the other hand, the broadcast communication transmits data to all receivable destinations by using ‘broadcast IP address (255.255.255.255)’. For example, suppose that the user transmits data to destination A, B, and C. The unicast communication transmits each destination A, B, and C at each time. At this time, the ARP_TO can also occur when the user gets the destination hardware address of destinations A, B and C. User cannot transmit data to destinations which have ARP_TO. The broadcast communication can simultaneously transmit data to destination A, B and C at one time by using “255.255.255.255” or “local address | (~subnet address)”
IP address. At this time, there is no need to get the destination hardware address about destination A, B and C, and also ARPTO is not occurred.

**Note:** Broadcast IP

=> The Broadcast IP address can be obtained by performing a bit-wise logical OR operation between the bit complement of the subnet mask and the host’s IP address.

ex> If IP: “222.98.173.123” and the subnet mask: “255.255.255.0”, broadcast IP is “222.98.173.255”

<table>
<thead>
<tr>
<th>Description</th>
<th>Decimal</th>
<th>Binary</th>
</tr>
</thead>
<tbody>
<tr>
<td>HOST IP</td>
<td>222.098.173.123</td>
<td>11011110.01100010.10101101.01111011</td>
</tr>
<tr>
<td>Bit Complement Subnet mask</td>
<td>000.000.000.255</td>
<td>00000000.00000000.00000000.11111111</td>
</tr>
<tr>
<td>Bitwise OR</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Broadcast IP</td>
<td>222.098.173.255</td>
<td>11011110.01100010.10101101.11111111</td>
</tr>
</tbody>
</table>

**SOCKET Initialization**

For the UDP data communication, SOCKET initialization is required; it opens the SOCKET. The SOCKET open process is as followed. At first, choose one SOCKET among the 8 SOCKETS of W5200, then set the protocol mode (Sn_MR(P3:P0)) of the chosen SOCKET and set the source port number Sn_PORT0 for communication. Finally, execute the OPEN command. After the OPEN command, the state of Sn_SR is changed to SOCK_UDP. Then the SOCKET initialization is complete.

```cpp
{ 
    START:
    Sn_MR = 0x02;   /* sets UDP mode */
    Sn_PORT0 = source_port;  /* sets source port number */
    Sn_CR = OPEN;   /* sets OPEN command */

    /* wait until Sn_SR is changed to SOCK_UDP */
    if (Sn_SR != SOCK_UDP) Sn_CR = CLOSE; goto START;
}
```

**Check received data**

Check the reception of UDP data from destination. User can also check for received data via TCP communication. It is strongly recommended to use the second method because of the same reasoning from TCP. Please refer to the “5.2.1.1 TCP SERVER”.

```cpp
First method :
{
    if (Sn_IR(RECV) == ‘1’) Sn_IR(RECV) = ‘1’; goto Receiving Process stage;
}
```
Second Method:
{
    if (Sn_RX_RSR0 != 0x0000) goto Receiving Process stage;
}

Receiving process

Process the received UDP data in Internal RX memory.
The structure of received UDP data is as below.

<table>
<thead>
<tr>
<th>PACKET-INFO</th>
<th>DATA packet</th>
</tr>
</thead>
<tbody>
<tr>
<td>Destination IP Address</td>
<td>Destination Port number</td>
</tr>
<tr>
<td>4 Bytes</td>
<td>2 Bytes</td>
</tr>
</tbody>
</table>

Figure 13 The Received UDP data Format

The received UDP data consists of 8 bytes PACKET-INFO, and DATA packet. The PACKET-INFO contains transmitter’s information (IP address, Port number) and the length of DATA packet. The UDP can receive UDP data from many others. User can classify the transmitter by transmitter’s information of PACKET-INFO. It also receives broadcast SOCKET by using “255.255.255.255” IP address. So the host should ignore unwanted reception by analysis of transmitter’s information.

If the DATA size of Socket n-th is larger than Internal RX memory free size, user cannot receive that DATA and also cannot receive fragmented DATA.

{ /* calculate offset address */
    src_mask = Sn_RX_RD & gSn_RX_MASK;  // src_mask is offset address
    /* calculate start address(physical address) */
    src_ptr = gSn_RX_BASE + src_mask;    // src_ptr is physical start address

    /* read head information (8 bytes) */
    header_size = 8;
    /* if overflow SOCKET RX memory */
    if ( (src_mask + header_size) > (gSn_RX_MASK + 1) )
    {
        /* copy upper_size bytes of src_ptr to header_addr*/
        upper_size = (gSn_RX_MASK + 1) - src_mask;
        memcpy(src_ptr, header, upper_size);
    }
/* update header_addr */
    header_addr += upper_size;
/* copy left_size bytes of gSn_RX_BASE to header_address */
    left_size = header_size - upper_size;
    memcpy(gSn_RX_BASE, header, left_size);
/* update src_mask */
    src_mask = left_size;
}
else{
    /* copy header_size bytes of get_start_address to header_address */
    memcpy(src_ptr, header, header_size);
    /* update src_mask */
    src_mask += header_size;
}
/* update src_ptr */
    src_ptr = gSn_RX_BASE + src_mask;

/* save remote peer information & received data size */
    peer_ip = header[0 to 3];
    peer_port = header[4 to 5];
    get_size = header[6 to 7];

/* if overflow SOCKET RX memory */
if ((src_mask + get_size) > (gSn_RX_MASK + 1)) {
    /* copy upper_size bytes of src_ptr to destination_address */
    upper_size = (gSn_RX_MASK + 1) - src_mask;
    memcpy(src_ptr, destination_addr, upper_size);
    /* update destination_addr */
    destination_addr += upper_size;
    /* copy left_size bytes of gSn_RX_BASE to destination_address */
    left_size = get_size - upper_size;
    memcpy(gSn_RX_BASE, destination_addr, left_size);
} else {
    /* copy len bytes of src_ptr to destination_address */
    memcpy(src_ptr, destination_addr, get_size);
} /* increase Sn_RX_RD as length of len + header_size */
Sn_RX_RD = Sn_RX_RD + header_size + get_size;
/* set RECV command */
Sn_CR = RECV;
}
Check send data / sending process

The size of DATA that the user wants to transmit cannot be larger than Internal TX memory. If it is larger than MTU, it is automatically divided by MTU unit and transmitted. The Sn_DIPR0 is set “255.255.255.255” when user wants to broadcast.

```c
{  // first, get the free TX memory size */
    FREESIZE:
        freesize = Sn_TX_FSR0;
        if (freesize<len) goto FREESIZE;  // len is send size

    /* Write the value of remote_ip, remote_port to the Socket n-th Destination IP Address Register(Sn_DIPR), Socket n-th Destination Port Register(Sn_DPORT). */
        Sn_DIPR0 = remote_ip;
        Sn_DPORT0 = remote_port;

    /* calculate offset address */
        dst_mask = Sn_TX_WR0 & gSn_TX_MASK;  // dst_mask is offset address

    /* calculate start address(physical address) */
        dst_ptr = gSn_TX_BASE + dst_mask;  // dst_ptr is physical start address

    /* if overflow SOCKETTX memory */
        if ( (dst_mask + len) > (gSn_TX_MASK + 1) )
            {
                /* copy upper_size bytes of source_address to dst_ptr */
                    upper_size = (gSn_TX_MASK + 1) - dst_mask;
                    memcpy(src_ptr, destination_addr, upper_size);

                /* update source_address*/
                    source_address += upper_size;

                /* copy left_size bytes of source_address to gSn_TX_BASE */
                    left_size = send_size - upper_size;
                    memcpy(src_ptr, destination_addr, left_size);
            }
        else
            {
                /* copy len bytes of source_address to dst_ptr */
                    memcpy(src_ptr, destination_addr, len);
            }

    /* increase Sn_TX_WR0 as length of len */
        Sn_TX_WR0 += len;
```
/* set SEND command */
Sn_CR = SEND;
}

Check complete sending / Timeout

To transmit the next data, user must check that the prior SEND command is completed. The larger the data size, the more time to complete the SEND command. Therefore, the user must properly divide the data to transmit. The ARP_TO can occur when user transmits UDP data. If ARP_TO occurs, the UDP data transmission has failed.

First method :
{
/* check SEND command completion */
while(Sn_IR(SENDOK)=='0') /* wait interrupt of SEND completion */
{
/* check ARP_TO */
if (Sn_IR(TIMEOUT)=='1') Sn_IR(TIMEOUT)='1'; goto Next stage;
}
Sn_IR(SENDOK) = '1'; /* clear previous interrupt of SEND completion */
}

Second method :
{
If (Sn_CR == 0x00) transmission is completed.
If (Sn_IR(TIMEOUT bit) == ‘1’) goto next stage;
/* In this case, if the interrupt of Socket n-th is activated, interrupt occurs. Refer to Interrupt Register(IR), Interrupt Mask Register (IMR) and Socket n-th Interrupt Register (Sn_IR). */
}

Check Finished / SOCKET close

If user doesn’t need the communication any more, close the Socket n-th.

{ /* clear remained interrupts */
Sn_IR = 0x00FF;
   IR(n) = ‘1’;
/* set CLOSE command */
Sn_CR = CLOSE;
}
Multicast

The broadcast communication communicates with many and unspecified others. But the multicast communication communicates with many specified others who registered at a multicast-group. Suppose that A, B, and C are registered at a specified multicast-group. If user transmits data to multicast-group (contains A), B and C also receive the DATA for A. To use multicast communication, the destination list registers to multicast-group by using IGMP protocol. The multicast-group consists of ‘Group hardware address,’ ‘Group IP address,’ and ‘Group port number.’ User cannot change the ‘Group hardware address’ and ‘Group IP address.’ But the ‘Group port number’ can be changed.

The ‘Group hardware address’ is selected at the assigned range (From “01:00:5e:00:00:00” to “01:00:5e:7f:ff:ff”) and the ‘Group IP address’ is selected in D-class IP address (From “224.0.0.0” to “239.255.255.255”, please refer to the website; http://www.iana.org/assignments/multicast-addresses). When selecting, the upper 23bit of 6bytes ‘Group hardware address’ and the 4bytes ‘Group IP address’ must be the same. For example, if the user selects the ‘Group IP address’ to “244.1.1.11,” the ‘Group hardware address’ is selected to “01:00:5e:01:01:0b.” Please refer to the “RFC1112” (http://www.ietf.org/rfc.html).

In the W5200, IGMP processing to register the multicast-group is internally (automatically) processed. When the user opens the Socket n-th with multicast mode, the “Join” message is internally transmitted. If the user closes it, the “Leave” message is internally transmitted. After the SOCKET opens, the “Report” message is periodically and internally transmitted when the user communicates.

The W5200 support IGMP version 1 and version 2 only. If user wants use an updated version, the host processes IGMP directly by using the IPRAW mode SOCKET.

SOCKET Initialization

Choose one SOCKET for multicast communication among 8 SOCKETS of W5200. Set the Sn_DHAR0 to ‘Multicast-group hardware address’ and set the Sn_DIPR0 to ‘Multicast-group IP address.’ Then set the Sn_PORT0 and Sn_DPORT0 to ‘Multicast-group port number.’ Set the Sn_MR(P3:P0) to UDP and set the Sn_MR(MULTI) to ‘1.’ Finally, execute OPEN command. If the state of Sn_SR is changed to SOCK_UDP after the OPEN command, the SOCKET initialization is completed.

```c
{"START:
    /* set Multicast-Group information */
    Sn_DHAR0 = 0x01;  /* set Multicast-Group H/W address(01:00:5e:01:01:0b) */
    Sn_DHAR1 = 0x00;
    Sn_DHAR2 = 0x5E;
}
Check received data

Refer to the “5.2.2.1 Unicast & Broadcast.”

Receiving process

Refer to the “5.2.2.1 Unicast & Broadcast.”

Check send data / Sending Process

Since the user sets the information about multicast-group at SOCKET initialization, user does not need to set IP address and port number for destination any more. Therefore, copy the transmission data to internal TX memory and executes SEND command.

```c
{
    /* first, get the free TX memory size */
    FREESIZE:
    freesize = Sn_TX_FSR;
    if (freesize<len) goto FREESIZE; // len is send size

    /* calculate offset address */
    dst_mask = Sn_TX_WRO & gSn_TX_MASK; // dst_mask is offset address

    /* calculate start address(physical address) */
    dst_ptr = gSn_TX_BASE + dst_mask; // dst_ptr is physical start address

    /* if overflow SOCKETTX memory */
```
if ( (dst_mask + len) > (gSn_TX_MASK + 1) )
{
    /* copy upper_size bytes of source_addr to destination_address */
    upper_size = (gSn_TX_MASK + 1) - dst_mask;
    wizmemcpy((0x000000 + source_addr), (0xFE0000 + dst_ptr), upper_size);
    /* update source_addr*/
    source_addr += upper_size;
    /* copy left_size bytes of source_addr to gSn_TX_BASE */
    left_size = len - upper_size;
    wizmemcpy( source_addr, gSn_TX_BASE, left_size);
}
else
{
    /* copy len bytes of source_addr to dst_ptr */
    wizmemcpy( source_addr, dst_ptr, len);
}
/* increase Sn_TX_WR as length of len */
Sn_TX_WR0 += send_size;
/* set SEND command */
Sn_CR = SEND;
}

Check complete sending / Timeout
Since the host manages all protocol process for data communication, timeout cannot occur.
{
    /* check SEND command completion */
    while(S0_IR(SENDOK)="0"); /* wait interrupt of SEND completion */
    S0_IR(SENDOK) = '1'; /* clear previous interrupt of SEND completion */
}

Check finished / SOCKET close
Refer to the “5.2.2.1 Unicast & Broadcast.”
5.2.3 IPRAW

IPRAW is data communication using TCP, UDP, and IP layers, which are the lower protocol layers. IPRAW supports IP layer protocol such as ICMP (0x01) and IGMP (0x02) according to the protocol number. The ‘ping’ of ICMP or IGMP v1/v2 is already included in W5200 by hardware logic. But if the user needs, the host can directly process the IPRAW by opening the Socket n-th to IPRAW. In the case of using IPRAW mode, user must set the protocol number field of the IP header to what the user wants to use. The protocol number is defined by IANA. Refer to the web ([http://www.iana.org/assignments/protocol-numbers](http://www.iana.org/assignments/protocol-numbers)). The protocol number must be configured to Sn_PROTO before ‘SOCKET open.’ In IPRAW mode, W5200 does not support TCP (0x06) or UDP (0x11) protocol number. The SOCKET communication of IPRAW mode only allows the communication of an assigned protocol number. The ICMP SOCKET cannot receive unassigned protocol data except assigned protocol data such as IGMP.

![Figure 14 IPRAW Operation Flow](image)

**Figure 14 IPRAW Operation Flow**

**SOCKET Initialization**

Select the SOCKET and set the protocol number. Then set the Sn_MR(P3:P0) to IPRAW mode and execute ‘OPEN’ command. If the Sn_SR is changed to SOCK_IPRAW after the ‘OPEN’ command, the SOCKET initialization is completed.

```c
{  
  START:
  /* sets Protocol number */
  /* The protocol number is used in Protocol Field of IP Header. */
  Sn_PROTO = protocol_num;
}
```

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Check received data
Refer to the “5.2.2.1 Unicast & Broadcast.”

Receiving process
Process the IPRAW data which is received in internal RX memory. The structure of received IPRAW data is as below.

<table>
<thead>
<tr>
<th>PACKET-INFO</th>
<th>DATA packet</th>
</tr>
</thead>
<tbody>
<tr>
<td>Destination IP Address</td>
<td>Byte size of DATA packet</td>
</tr>
<tr>
<td>4 Bytes</td>
<td>2 Bytes</td>
</tr>
</tbody>
</table>

Figure 15 The receive IPRAW data Format

The IPRAW data consists 6 bytes PACKET-INFO and DATA packet. The PACKET-INFO contains information about the transmitter (IP address) and the length of the DATA-packet. The data reception of IPRAW is the same as UDP data reception except processing the port number of the transmitter in UDP PACKET-INFO. Refer to the “5.2.2.1 Unicast & Broadcast.” If the transmitted DATA size is larger than RX memory free size of Socket n-th, user cannot receive that DATA and also cannot receive fragmented DATA.

Checks send data / Sending process
The size of DATA which user wants to transmit cannot be larger than Internal TX memory and default MTU. The transmission of IPRAW data is the same as transmission of UDP data except setting ‘Destination port number’. Refer to the “5.2.2.1 Unicast & Broadcast.”

Complete sending / Timeout
Same as UDP, please refer to the “5.2.2 UDP.”

Check finished / SOCKET closed
Same as UDP, please refer to the “5.2.2 UDP.”
5.2.4 MACRAW

The MACRAW communication is based on Ethernet MAC, and it can flexibly use upper layer protocol to suit the host’s needs.

The MACRAW mode can only be used with a SOCKET. If the user uses the SOCKET in MACRAW mode, not only can it use the SOCKET1~7 in the ‘Hardwired TCP/IP stack’, but it can also be used as a NIC (Network Interface Controller). Therefore, any SOCKET1~7 can be used with ‘Software TCP/IP stack’. Since the W5200 supports ‘Hardwired TCP/IP stack’ and ‘Software TCP/IP stack’, it calls ‘Hybrid TCP/IP stack’. If user wants more SOCKETS beyond the supported 8 SOCKETS, the SOCKET in which the user wants high performance should be utilizing the ‘Hardwired TCP/IP stack’, and the others should be using ‘Software TCP/IP stack’ by MACRAW mode. So it overcomes the limited capacity of 8 SOCKETS. The SOCKET of MACRAW mode can process all protocols except using in SOCKET1~7. Since the MACRAW communication is pure Ethernet packet communication (there is no other processing), the MACRAW designer should use the ‘Software TCP/IP stack’ to process the protocol. The MACRAW data should basically contain the 6bytes of ‘Source hardware address’, 6bytes of ‘destination hardware address’ and 2bytes of ‘Ethernet type’ because it is based on Ethernet MAC.

![Figure 16 MACRAW Operation Flow](image-url)
SOCKET Initialization

Select the SOCKET and set the SN_MR(P3:P0) to MACRAW mode. Then execute the ‘OPEN’ command. After the ‘OPEN’ command, if the Sn_SR is successfully changed to ‘SOCK_MACRAW’, the SOCKET initialization is completed. Since all information about communication (Source hardware address, Source IP address, Source port number, Destination hardware address, Destination IP address, Destination port number, Protocol header, etc.) is in the ‘MACRAW data’, there is no more register setting.

```
{  
  START:
  /* sets MAC raw mode */
  S0_MR = 0x04;
  /* sets OPEN command */
  S0_CR = OPEN;
  /* wait until Sn_SR is changed to SOCK_MACRAW */
  if (Sn_SR != SOCK_MACRAW) S0_CR = CLOSE; goto START;
}
```

Check received data

Refer to the “5.2.2.1 Unicast & Broadcast.”

Receiving process

Process the MACRAW data of the SOCKET which received it in internal RX memory.

The structure of the MACRAW data is as below:

<table>
<thead>
<tr>
<th>PACKET-INFO</th>
<th>DATA packet</th>
<th>CRC</th>
</tr>
</thead>
<tbody>
<tr>
<td>Byte size of DATA packet</td>
<td>Real Data</td>
<td>Cyclic Redundancy Check</td>
</tr>
<tr>
<td>2 Bytes</td>
<td>Source MAC (6Bytes)</td>
<td>Destination MAC (6Bytes)</td>
</tr>
</tbody>
</table>

**Figure 17 The received MACRAW data Format**

The MACRAW data consists of ‘PACKET-INFO,’ ‘DATA packet’ and 4 bytes CRC. The ‘PACKET-INFO’ is the length of the DATA packet. The ‘DATA packet’ consists of 6 bytes ‘Destination MAC address,’ 6 bytes ‘Source MAC address’ and 2 bytes ‘Type,’ 46-1500 bytes ‘Payload.’ The ‘Payload’ of DATA packet consists of Internet protocol such as ARP, IP according to the ‘Type.’ The details of ‘Type’ please refer to the web: (http://www.iana.org/assignments/ethernet-numbers)

```
{  
  /* calculate offset address */
  src_mask = Sn_RX_RD & gSn_RX_MASK;   // src_mask is offset address
  /* calculate start address(physical address) */
}
```
src_ptr = gSn_RX_BASE + src_mask;  // src_ptr is physical start address
/* get the received size */
len = get_Byte_Size.Of_Data.packet  // get Byte size of DATA packet from Packet-INFO
/* if overflow SOCKET RX memory */
If((src_mask + len) > (gSn_RX_MASK + 1))
{
    /* copy upper_size bytes of get_start_address to destination_address */
    upper_size = (gSn_RX_MASK + 1) - src_mask;
    memcpy(src_ptr, dst_addr, upper_size);
    /* update destination_address */
    dst_addr += upper_size;
    /* copy left_size bytes of gSn_RX_BASE to destination_address */
    left_size = len - upper_size;
    memcpy(src_ptr, dst_addr, left_size);
}
else
{
    /* copy len bytes of src_ptr to destination_address */
    memcpy(src_ptr, dst_addr, len);
}
/* increase Sn_RX_RD as length of len */
Sn_RX_RD += len;
/* extract 4 bytes CRC from internal RX memory and then ignore it */
memcpy(src_ptr, dst_addr, len);
/* set RECV command */
Sn_CR = RECV;

<Notice>
If the free size of the internal RX memory is smaller than the MACRAW data, a problem may occasionally occur where some parts of that PACKET-INFO and DATA packet are stored to the internal RX memory. Since the problem occurs as an analysis error for PACKET-INFO, it cannot process the MACRAW data correctly. The closer the internal RX memory is to being full, the higher the probability is for an error to occur. This problem can be resolved if user allows some loss of the MACRAW data.
The solution is as follows:
• Process the internal RX memory as fast as possible to prevent that it closes to full.
• Reduce the receiving load by reception only its MACRAW data by setting the MF (MAC Filter) bit of S0_MR in sample code of SOCKET initialization.
If the free size of the internal RX memory is smaller than \(1528 - \text{Default MTU(1514)} + \text{PACKET INFO(2)} + \text{DATA packet(8)} + \text{CRC(4)}\), close the SOCKET and process all received data. Then reopen the SOCKET. After closing the SOCKET, the received MACRAW data from closing time can be lost.

```c
/* check the free size of internal RX memory */
if((Sn_RXMEM_SIZE(0) * 1024) - Sn_RX_RSR0(0) < 1528)
{
    recved_size = Sn_RX_RSR0(0);  /* backup Sn_RX_RSR */
    Sn_CR0 = CLOSE;   /* SOCKET Closed */
    while(Sn_SR != SOCK_CLOSED); /* wait until SOCKET is closed */
    /* process all data remained in internal RX memory */
    while(recved_size> 0)
    {
        /* calculate offset address */
        src_mask = Sn_RX_RD&gSn_RX_MASK;   // src_mask is offset address
        /* calculate start address(physical address) */
        src_ptr = gSn_RX_BASE + src_mask;  // src_ptr is physical start address
        /* if overflow SOCKET RX memory */
        If((src_mask + len) > (gSn_RX_MASK + 1))
        {
            /* copy upper_size bytes of get_start_address to destination_address */
            upper_size = (gSn_RX_MASK + 1) - src_mask;
            memcpy(src_ptr, dst_addr, upper_size);
            /* update destination_address */
            dst_address += upper_size;
            /* copy left_size bytes of gSn_RX_BASE to destination_address */
            left_size = len - upper_size;
            memcpy(src_ptr, dst_addr, left_size);
        }
    }
}
```
else
{
  /* copy len bytes of src_ptr to destination_address */
  memcpy(src_ptr, dst_addr, len);

}
/* increase Sn_RX_RD as length of len */
Sn_RX_RD += len;
/* extract 4 bytes CRC from internal RX memory and then ignore it */
memcpy(src_ptr, dst_addr, len);
/* calculate the size of remained data in internal RX memory*/
recved_size = recved_size - 2 - len - 4;
}
/* Reopen the SOCKET */
/* sets MAC raw mode with enabling MAC filter */
S0_MR = 0x44; /* or S0_MR = 0x04 */
/* sets OPEN command */
S0_CR = OPEN;
/* wait until Sn_SR is changed to SOCK_MACRAW */
while (Sn_SR != SOCK_MACRAW);
}
else /* process normally the DATA packet from internal RX memory */
{
  /* This block is same as the code of “Receiving process” stage*/
}
}

Check send data / sending process

The size of the data which the user wants to transmit cannot be larger than the internal TX memory and default MTU. The host generates the MACRAW data in the same format as the “Receiving process” data packet, and transmits it. At this time, if the size of the generated data is smaller than 60bytes, the transmitted Ethernet packet internally fills to 60bytes by “Zero padding” and then it is transmitted.

{
  /* first, get the free TX memory size */
FREESIZE:
  freesize = S0_TX_FSR;
  if (freesize<send_size) goto FREESIZE;
  /* calculate offset address */
  dst_mask = Sn_TX_WR0 &gSn_TX_MASK;    // dst_mask is offset address
  /* calculate start address(physical address) */
}
dst_ptr = gSn_TX_BASE + dst_mask;  // dst_ptr is physical start address

/* if overflow SOCKETTX memory */
if ( (dst_mask + len) > (gSn_TX_MASK + 1) )
{

/* copy upper_size bytes of source_addr to destination_address */
  upper_size = (gSn_TX_MASK + 1) - dst_mask;
  memcpy(src_ptr, dst_addr, upper_size);
  /* update source_addr*/
  source_addr += upper_size;

/* copy left_size bytes of source_addr to gSn_TX_BASE */
  left_size = len - upper_size;
  memcpy(src_ptr, dst_addr, left_size);
}
else
{
/* copy len bytes of source_addr to destination_address */
  memcpy(src_ptr, dst_addr, len);
}
/* increase Sn_TX_WR as length of len */
Sn_TX_WR += send_size;
/* set SEND command */
S0_CR = SEND;

Check complete sending
Since the host manages all protocol processors to communicate, the timeout can notoccur.

{
/* check SEND command completion */
while(S0_IR(SENDOK)=='0');  /* wait interrupt of SEND completion */
S0_IR(SENDOK) = '1';  /* clear previous interrupt of SEND completion */
}

Check finished / SOCKET close
Refer to the “5.2.2.1 Unicast & Broadcast.”
6 External Interface

For the communication with MCU, W5200 provides SPI I/F modes. For the communication with Ethernet PHY, MII is used.

6.1 SPI (Serial Peripheral Interface) mode
Serial Peripheral Interface Mode uses only four pins for data communication. Four pins are nSCS, SCLK, MOSI, and MISO.

![Figure 18 SPI Interface](image)

6.2 Device Operations
W5200 is controlled by a set of instruction that is sent from an external host, commonly referred to as the SPI Master. The SPI Master communicates with W5200 via the SPI bus, which is composed of four signal lines: Slave Chip Select (nSCS), Serial Clock (SCLK), MOSI (Master Out Slave In) and MISO (Master In Slave Out).

The SPI protocol defines four modes for its operation (Mode 0-3). Each mode differs according to the SCLK polarity and phase - how the polarity and phase control the flow of data on the SPI bus. The W5200 operates as SPI Slave device and supports the most common modes - SPI Mode 0 and 3.

The only difference between SPI Mode 0 and 3 is the polarity of the SCLK signal at the inactive state. With SPI Mode 0 and 3, data is always latched in on the rising edge of SCLK and always output on the falling edge of SCLK.
6.3 Process of using general SPI Master device

2. Configure nSCS as ‘High’ on inactive
3. Write target address for transmission on SPDR register (SPI Data Register).
4. Write OP code and data length for transmission on SPDR register.
5. Write desired data for transmission on SPDR register.
6. Configure nSCS as ‘Low’ (data transfer start)
7. Wait for reception complete
8. If all data transmission ends, configure nSCS as ‘High’

![Figure 19 W5200 SPI Frame Format](image)

![Figure 20 Address and OP/DATA Length Sequence Diagram](image)
READ Processing

The READ Processing Sequence Diagram is shown in Figure 20. The READ processing is entered by driving nSCS low, followed by the Address, the OP code, the Data Length and the Dummy data byte on MOSI. And then W5200 read the data byte on MISO. The Address, the OP/Data Length Sequence Diagram and the Data are shown in Figure 19. The OP code (OP) is defined type of the READ OP and WRITE OP. On OP = 0, the read operation is selected. Otherwise, On OP = 1, the write operation is selected.

In W5200 SPI mode, the Byte READ processing and the burst READ processing are provided. The Byte READ processing takes 4 instructions which is consist of the 16-bit Address, the 1-bit OP code(0x0), the 15-bit Data length and 8-bit Data. Otherwise, The Burst READ processing only takes the Data instruction after the setting of the burst read processing. To distinguish between the Byte READ and the burst READ processing, the Data length is used. If the Data length is '1,' the Byte READ processing is operated. Otherwise, the Burst READ Processing is operated when the Data length is more than two. The MISO pin should be selected by driving MISO low after the falling edge of the nSCS.

```
/* Pseudo Code for Read data of 8bit per packet */
#define data_read_command    0x00
uint16 addr;     // Address : 16bits
int16 data_len;   // Data length :15bits
uint8 data_buf[];  // Array for data
SpiSendData();   // Send data from MCU to W5200
SpiRecvData();   // Receive data from W5200 to MCU
```
ISR_DISABLE(); // Interrupt Service Routine disable
CSoff(); // CS=0, SPI start

// SpiSendData
SpiSendData(((addr+idx) & 0xFF00) >> 8); // Address byte 1
SpiSendData((addr+idx) & 0x00FF); // Address byte 2

// Data write command + Data length upper 7bits
SpiSendData((data_read_command| ((data_len& 0x7F00) >> 8)));
// Data length bottom 8bits
SpiSendData((data_len& 0x00FF));

// Read data: On data_len> 1, Burst Read Processing Mode.
for(int idx = 0; idx<data_len; idx++)
{
    SpiSendData(0); // Dummy data
    data_buf[idx] = SpiRecvData(idx); // Read data
}
CSon(); // CS=1, SPI end
ISR_ENABLE(); // Interrupt Service Routine disable
The WRITE Processing Sequence Diagram is shown in Figure 21. The WRITE processing is entered by driving nSCS low, followed by the Address, the OP code, the Data Length, and the Data byte on MOSI.

In W5200 SPI mode, the Byte WRITE processing and the Burst WRITE processing are provided. The Byte WRITE processing takes 4 instructions which is consist of the 16-bit Address, the 1-bit OP code (0x1), the 15-bit Data length and 8-bit Data. Otherwise, The Burst WRITE processing only takes the Data instruction after the setting of the Burst WRITE processing. To distinguish between the Byte WRITE and the Burst WRITE processing, the Data length is used. If the Data length is ‘1,’ the Byte WRITE processing is operated. Otherwise, the Burst WRITE Processing is operated when the Data length is more than two. The MOSI pin should be selected by driving MOSI low after the falling edge of the nSCS.

/* Pseudo Code for Write data of 8bit per packet */
#define data_write_command 0x80
uint16 addr;  // Address : 16bits
int16 data_len;  // Data length :15bits
uint8 data_buf[];  // Array for data

{  
  SpiSendData();  //Send data from MCU to W5200
  ISR_DISABLE();  // Interrupt Service Routine disable
CSoff(); // CS=0, SPI start

SpiSendData(((addr+idx) & 0xFF00) >> 8);  // Address byte 1
SpiSendData((addr+idx) & 0x00FF);  // Address byte 2

// Data write command + Data length upper 7bits
SpiSendData((data_write_command | ((data_len & 0x7F00) >> 8)));

// Data length bottom 8bits
SpiSendData((data_len & 0x00FF));

// Write data: On data_len> 1, Burst Write Processing Mode.
for(int idx = 0; idx<data_len; idx++)
    SpiSendData(data_buf[idx]);

CSon();  // CS=1, SPI end
IINCHIP_ISR_ENABLE();  // Interrupt Service Routine disable
}
7 Electrical Specifications

7.1 Absolute Maximum Ratings

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Rating</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VDD</td>
<td>DC Supply voltage</td>
<td>-0.5 to 3.63</td>
<td>V</td>
</tr>
<tr>
<td>VIN</td>
<td>DC input voltage</td>
<td>-0.5 to 5.5 (5V tolerant)</td>
<td>V</td>
</tr>
<tr>
<td>IIN</td>
<td>DC input current</td>
<td>±5</td>
<td>mA</td>
</tr>
<tr>
<td>TOP</td>
<td>Operating temperature</td>
<td>-40 to 85</td>
<td>°C</td>
</tr>
<tr>
<td>TSTG</td>
<td>Storage temperature</td>
<td>-55 to 125</td>
<td>°C</td>
</tr>
</tbody>
</table>

*COMMENT: Stressing the device beyond the “Absolute Maximum Ratings” may cause permanent damage.

7.2 DC Characteristics

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VDD</td>
<td>DC Supply voltage</td>
<td>Junction temperature is from -55°C to 125°C</td>
<td>2.97</td>
<td>3.63</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>VIH</td>
<td>High level input voltage</td>
<td></td>
<td>2.0</td>
<td>5.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>VIL</td>
<td>Low level input voltage</td>
<td></td>
<td>-0.3</td>
<td>0.8</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>VOH</td>
<td>High level output voltage</td>
<td>IOH = 4 ~8 mA</td>
<td>2.4</td>
<td>0.8</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>VOL</td>
<td>Low level output voltage</td>
<td>IOL = 4 ~8mA</td>
<td>0.4</td>
<td>0.8</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>II</td>
<td>Input Current</td>
<td>VIN = VDD</td>
<td>±5</td>
<td>µA</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

7.3 POWER DISSIPATION(Vcc 3.3V Temperature 25°C)

<table>
<thead>
<tr>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>100M Link</td>
<td>-</td>
<td>160</td>
<td>175</td>
<td>mA</td>
</tr>
<tr>
<td>10M Link</td>
<td>-</td>
<td>110</td>
<td>125</td>
<td>mA</td>
</tr>
<tr>
<td>Loss Link</td>
<td>-</td>
<td>125</td>
<td>140</td>
<td>mA</td>
</tr>
<tr>
<td>100M Transmitting</td>
<td>-</td>
<td>160</td>
<td>175</td>
<td>mA</td>
</tr>
<tr>
<td>10M Transmitting</td>
<td>-</td>
<td>110</td>
<td>125</td>
<td>mA</td>
</tr>
<tr>
<td>Power Down mode</td>
<td>-</td>
<td>2</td>
<td>4</td>
<td>mA</td>
</tr>
</tbody>
</table>
7.4 AC Characteristics

7.4.1 Reset Timing

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
<th>Min</th>
<th>Max</th>
</tr>
</thead>
<tbody>
<tr>
<td>TRC</td>
<td>Reset Cycle Time</td>
<td>2 us</td>
<td>-</td>
</tr>
<tr>
<td>TPL</td>
<td>nRST internal PLOCK</td>
<td>-</td>
<td>150 ms</td>
</tr>
</tbody>
</table>

Figure 23 Reset Timing

7.4.2 Crystal Characteristics

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency</td>
<td>25 MHz</td>
</tr>
<tr>
<td>Frequency Tolerance (at 25°C)</td>
<td>±30 ppm</td>
</tr>
<tr>
<td>Shunt Capacitance</td>
<td>7pF Max</td>
</tr>
<tr>
<td>Drive Level</td>
<td>59.12μW/MHz</td>
</tr>
<tr>
<td>Load Capacitance</td>
<td>27pF</td>
</tr>
<tr>
<td>Aging (at 25°C)</td>
<td>±3ppm / year Max</td>
</tr>
</tbody>
</table>

nRST
PLOCK (Internal)
### 7.4.3 SPI Timing

![Figure 24 SPI Timing](image)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
<th>Min</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>$F_{SCK}$</td>
<td>SCK Clock Frequency</td>
<td></td>
<td>80</td>
<td>MHz</td>
</tr>
<tr>
<td>$T_{WH}$</td>
<td>SCK High Time</td>
<td>6</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{WL}$</td>
<td>SCK Low Time</td>
<td>6</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{CS}$</td>
<td>nSCS High Time</td>
<td>5</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{CSS}$</td>
<td>nSCS Hold Time</td>
<td>5</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{CSH}$</td>
<td>nSCS Hold Time</td>
<td>5</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{DS}$</td>
<td>Data In Setup Time</td>
<td>3</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{DH}$</td>
<td>Data In Hold Time</td>
<td>3</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{OV}$</td>
<td>Output Valid Time</td>
<td></td>
<td>5</td>
<td>ns</td>
</tr>
<tr>
<td>$T_{OH}$</td>
<td>Output Hold Time</td>
<td>0</td>
<td></td>
<td>ns</td>
</tr>
<tr>
<td>$T_{CHZ}$</td>
<td>nSCS High to Output Hi-Z</td>
<td>5</td>
<td></td>
<td>ns</td>
</tr>
</tbody>
</table>
### 7.4.4 Transformer Characteristics

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Transmit End</th>
<th>Receive End</th>
</tr>
</thead>
<tbody>
<tr>
<td>Turn Ratio</td>
<td>1:1</td>
<td>1:1</td>
</tr>
<tr>
<td>Inductance</td>
<td>350 μH</td>
<td>350 μH</td>
</tr>
</tbody>
</table>

In case of using internal PHY mode, be sure to use symmetric transformer in order to support Auto MDI/MDIX (Crossover).

**Figure 25 Transformer Type**

[Diagram showing Transformer Types]
8 IR Reflow Temperature Profile (Lead-Free)

Moisture Sensitivity Level : 3
Dry Pack Required: Yes

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Average Ramp-Up Rate (Ts_max to Tp)</td>
<td>3° C/second max.</td>
</tr>
<tr>
<td>Preheat</td>
<td></td>
</tr>
<tr>
<td>- Temperature Min (Ts_min)</td>
<td>150 °C</td>
</tr>
<tr>
<td>- Temperature Max (Ts_max)</td>
<td>200 °C</td>
</tr>
<tr>
<td>- Time (ts_min to ts_max)</td>
<td>60-120 seconds</td>
</tr>
<tr>
<td>Time maintained above:</td>
<td></td>
</tr>
<tr>
<td>- Temperature (TL)</td>
<td>217 °C</td>
</tr>
<tr>
<td>- Time (tL)</td>
<td>60-150 seconds</td>
</tr>
<tr>
<td>Peak/Classification Temperature (Tp)</td>
<td>265 + 0/-5°C</td>
</tr>
<tr>
<td>Time within 5 °C of actual Peak Temperature (tp)</td>
<td>30 seconds</td>
</tr>
<tr>
<td>Ramp-Down Rate</td>
<td>6 °C/second max.</td>
</tr>
<tr>
<td>Time 25 °C to Peak Temperature</td>
<td>8 minutes max.</td>
</tr>
</tbody>
</table>

Figure 26 IR Reflow Temperature
9 Package Descriptions

Figure 27 Package Dimensions

Note:

1. All dimensions are in millimeters.
2. Die thickness allowable is 0.0304 mm MAXIMUM (0.012 Inches MAXIMUM)
4. Dimension applies to plated terminal and is measured between 0.20 and 0.25 mm from terminal tip.
5. The pin #1 identifier must be placed on the top surface of the package by using indentation mark or other feature of package body.
6. Exact shape and size of this feature is optional.
7. Package warpage max 0.08 mm.
8. Applied for exposed pad and terminals. Exclude embedding part of exposed pad from measuring
9. Applied only to terminals
10. Package corners unless otherwise specified are R0.175± 0.025mm
## Document History Information

<table>
<thead>
<tr>
<th>Version</th>
<th>Date</th>
<th>Descriptions</th>
</tr>
</thead>
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<tr>
<td>Ver. 1.0.0</td>
<td>Mar2011</td>
<td>Released with W5200 Launching</td>
</tr>
<tr>
<td>Ver. 1.1.0</td>
<td>13MAR2011</td>
<td>Changed IMR address (0x16 to 0x36) (P.14, P.18)</td>
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<td></td>
<td>Changed IMR2 address (0x36 to 0x16) (P.14, P.22)</td>
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<tr>
<td>Ver. 1.2.0</td>
<td>22APR2011</td>
<td>Fixed the description of RSV at 1.3 Miscellaneous Signals (P.10)</td>
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<td>Fixed the values of typical at 7.3 power dissipation (P.77)</td>
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<tr>
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<td>Added the values of maximum at 7.3 power dissipation (P.77)</td>
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<td>Ver. 1.2.1</td>
<td>2AUG2011</td>
<td>Fixed the description of READ processing at 6.3 Processing of using general SPI Master device (P.73)</td>
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<tr>
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<td>Fixed the Block Diagram (P.4)</td>
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<tr>
<td>Ver. 1.2.3</td>
<td>3FEB2012</td>
<td>Added the Figure of XTAL_VDD at 1.4 Power Supply Signals (P.11)</td>
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<tr>
<td>Ver. 1.2.4</td>
<td>16FEB2012</td>
<td>Fixed the Pin names and sequence diagrams of READ processing and WRITE processing at 6.3 Processing of using general SPI Master device (P.73, 75)</td>
</tr>
<tr>
<td>Ver. 1.2.5</td>
<td>12APR2012</td>
<td>Corrects some miss phrase and words. Corrects the figure of SPI frame format (P.72)</td>
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</table>

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